

软件分析

南京大学

计算机科学与技术系

程序设计语言与

静态分析研究组

李樾 谭添

Static Program Analysis

Interprocedural Analysis

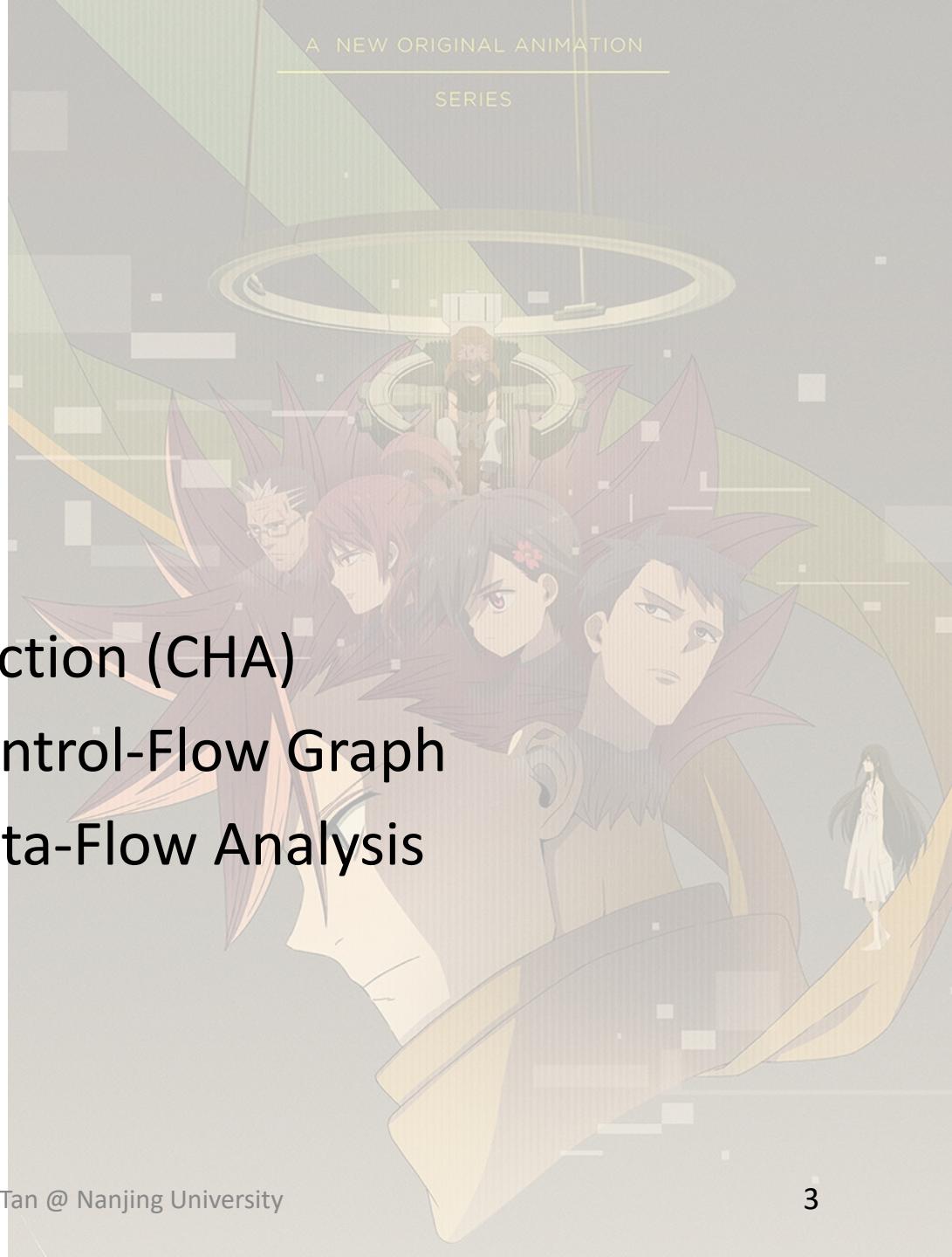
Nanjing University

Tian Tan

2021

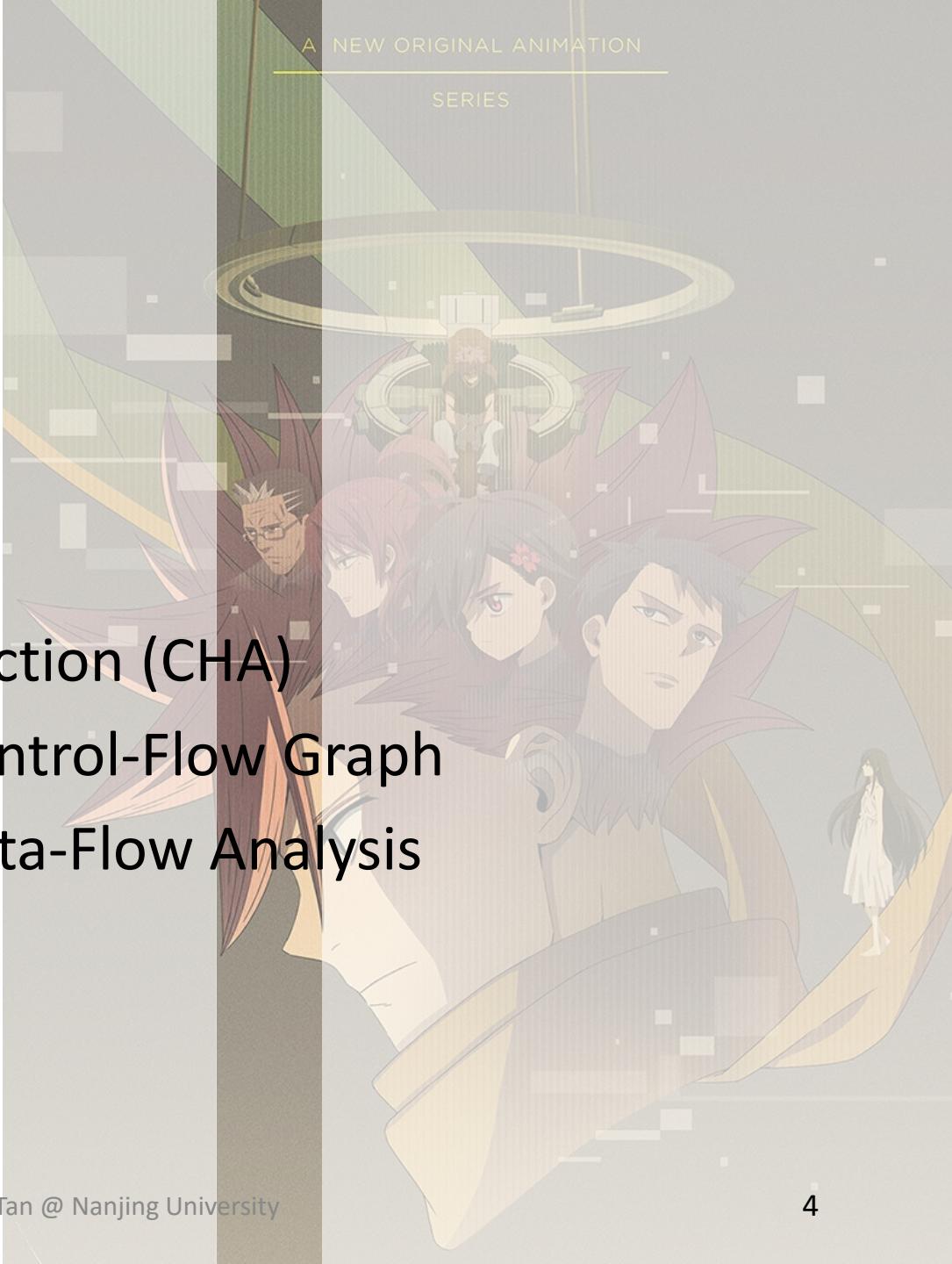
Contents

1. Motivation
2. Call Graph Construction (CHA)
3. Interprocedural Control-Flow Graph
4. Interprocedural Data-Flow Analysis



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Motivation of Interprocedural Analysis

Constant Propagation

So far, all analyses we learnt are **intraprocedural**.
How to deal with method calls?

```
void foo() {  
    → int n = bar(42);  
}
```

```
int bar(int x) {  
    → int y = x + 1;  
    return 10;  
}
```

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 - $x = \text{NAC}$, $y = \text{NAC}$
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void foo() {  
    int n = bar(42);  
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int bar(int x){  
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Return edges: A dashed red arrow points from the assignment `n = bar(42);` back to the variable `n`.
Call edges: A dashed blue arrow points from the call `bar(42)` to the entry point of the `bar` function.

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For better precision, we need **Interprocedural analysis**: propagate data-flow information along **interprocedural control-flow edges** (i.e., call and return edges)

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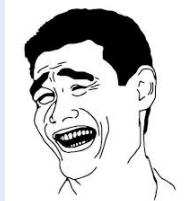
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- (i.e., call and return edges)
- $x = 42$, $y = 43$
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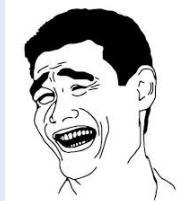
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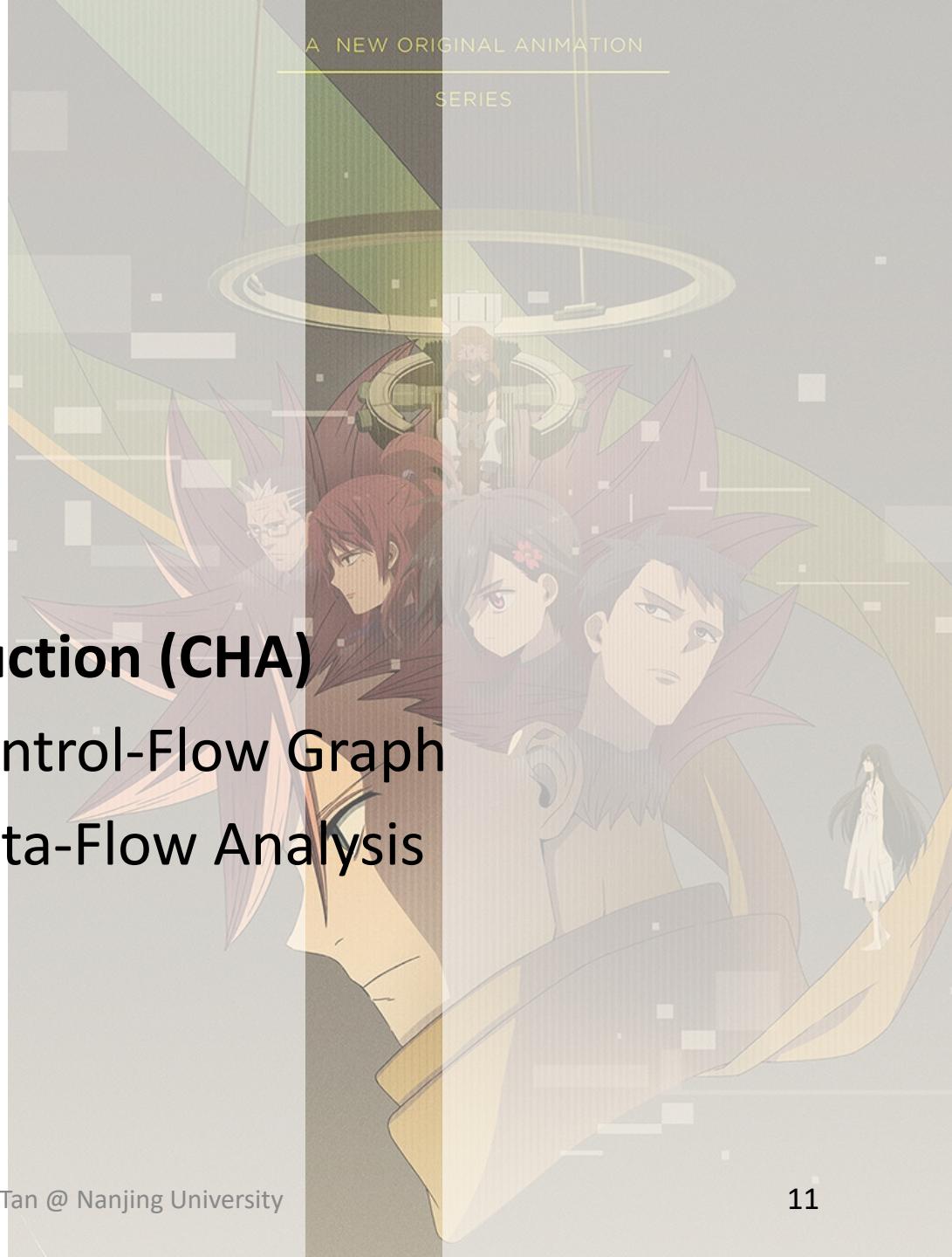
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To perform interprocedural analysis,
we need **call graph**

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Call Graph

A representation of calling relationships in the program

- Essentially, a call graph is a **set of call edges** from call-sites to their target methods (callees)

Call Graph

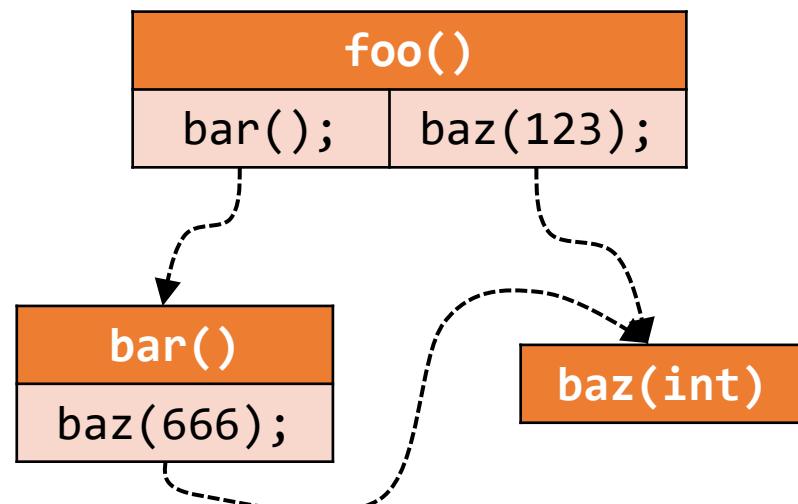
A representation of calling relationships in the program

- Essentially, a call graph is a **set of call edges** from call-sites to their target methods (callees)

```
void foo() {  
    bar();  
    baz(123);  
}
```

```
void bar(int x) {  
    baz(666);  
}
```

```
void baz() { }
```



Applications of Call Graph

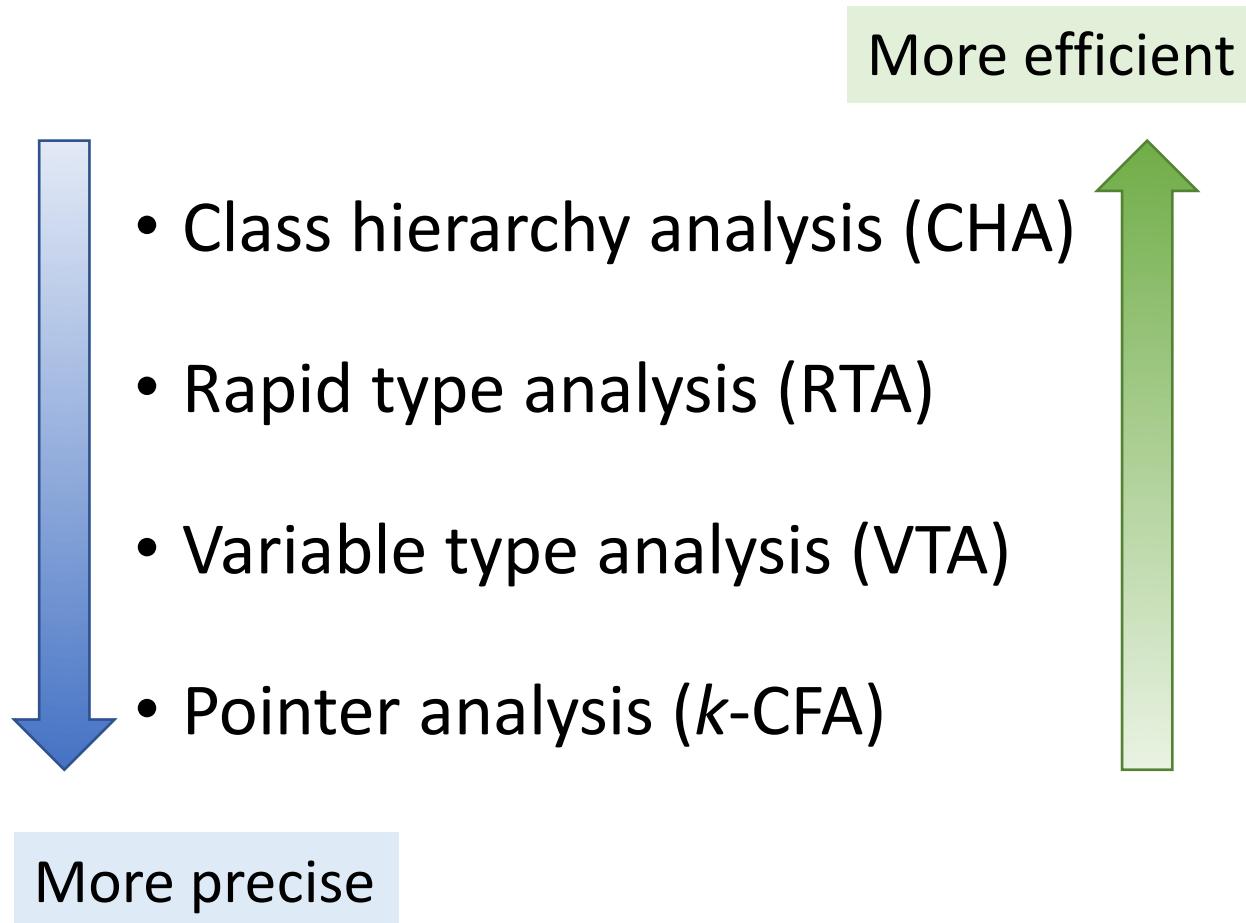
- Foundation of all interprocedural analyses
- Program optimization
- Program understanding
- Program debugging
- Program testing
- And many more ...

Call graph is **VERY important**
program information

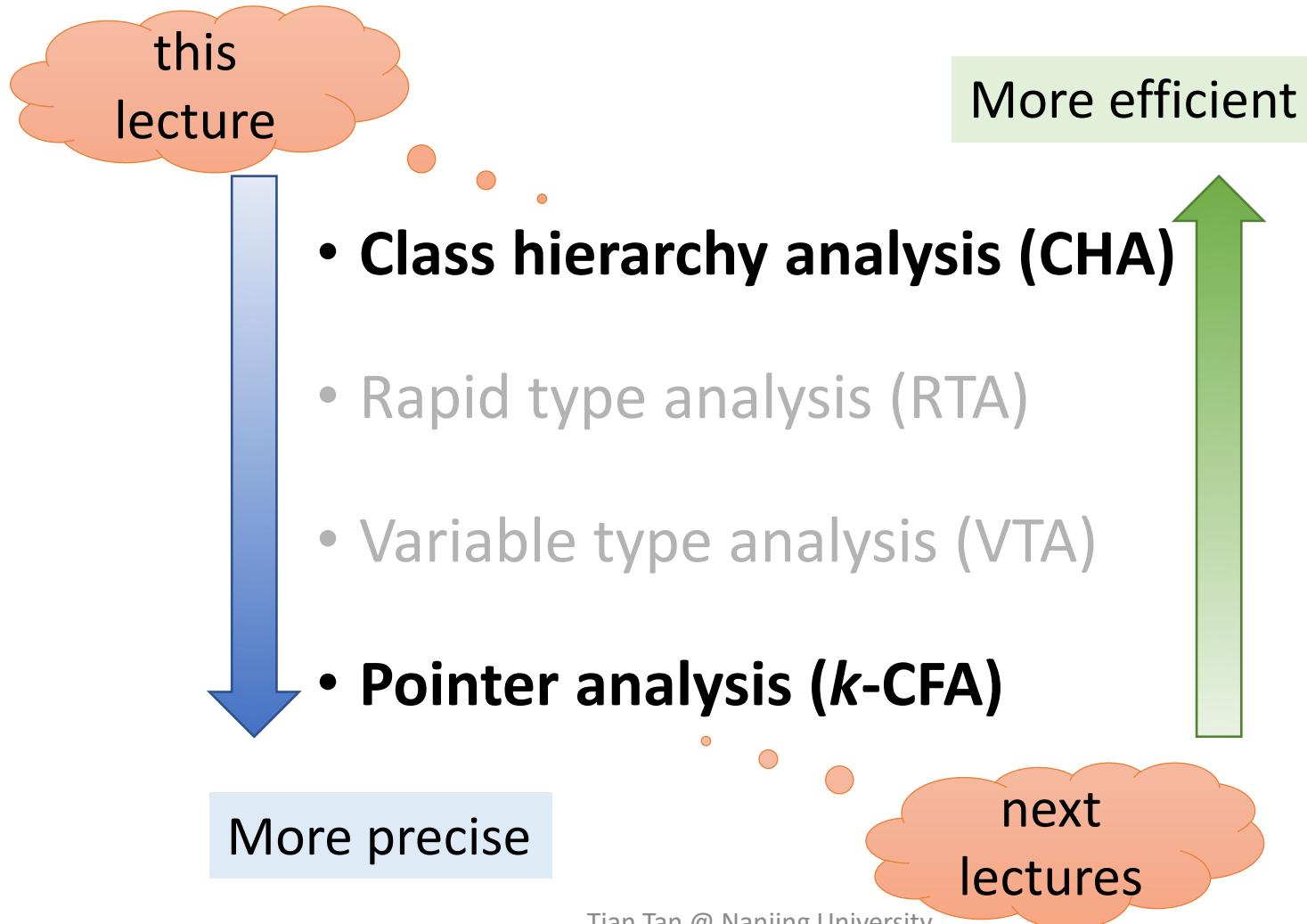
Call Graph Construction for OOPs (focus on Java)

- Class hierarchy analysis (CHA)
- Rapid type analysis (RTA)
- Variable type analysis (VTA)
- Pointer analysis (k -CFA)

Call Graph Construction for OOPs (focus on Java)



Call Graph Construction for OOPLs (focus on Java)



Method Calls (Invocations) in Java

	Static call	Special call	Virtual call
Instruction	<code>invokestatic</code>	<code>invokespecial</code>	<code>invokeinterface</code> <code>invokevirtual</code>

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Key to call graph construction for OOPs

Method Dispatch of Virtual Calls

During run-time, a virtual call is resolved based on

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Method Dispatch of Virtual Calls

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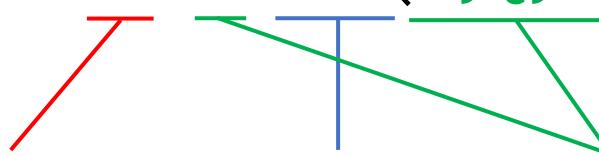
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In this lecture, a **signature** acts as an identifier of a method

```
class C {  
    T foo(P p, Q q, R r) { ... }  
}
```

`<C: T foo(P, Q, R)>`



- Signature = **class type** + **method name** + **descriptor**
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Method Dispatch of Virtual Calls

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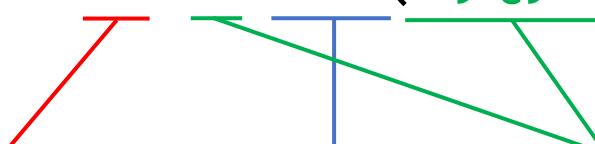
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```
class C {  
    T foo(P p, Q q, R r) { ... }  
}
```

`<C: T foo(P, Q, R)>`

`C.foo(P, Q, R)` for short

- 
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Method Dispatch of Virtual Calls

During run-time, a virtual call is resolved based on

1. type of the receiver object (pointed by o): c
2. method signature at the call site: m

$o^1.\text{foo}(\dots)^2;$

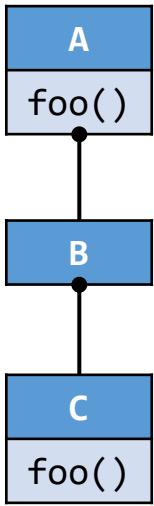
We define function $\text{Dispatch}(c, m)$ to simulate the procedure of run-time method dispatch

$$\text{Dispatch}(c, m) = \begin{cases} m', & \text{if } c \text{ contains non-abstract method } m' \text{ that} \\ & \text{has the same } \underline{\text{name}} \text{ and } \underline{\text{descriptor}} \text{ as } m \\ \text{Dispatch}(c', m), & \text{otherwise} \end{cases}$$

where c' is superclass of c

$\langle C: \underline{T \text{ foo}(P, Q, R)} \rangle$

Dispatch: An Example



```
class A {  
    void foo() {...}  
}  
  
class B extends A {  
}  
  
class C extends B {  
    void foo() {...}  
}
```

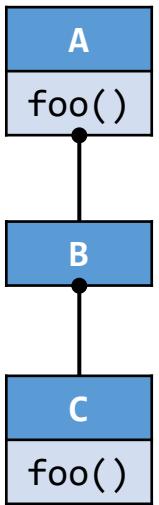
```
void dispatch() {  
    A x = new B();  
    x.foo();?  
  
    A y = new C();  
    y.foo();  
}
```

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$\text{Dispatch}(B, A.\text{foo}()) = ?$

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void dispatch() {  
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    x.foo();  
  
    A y = new C();  
    y.foo();?  
}
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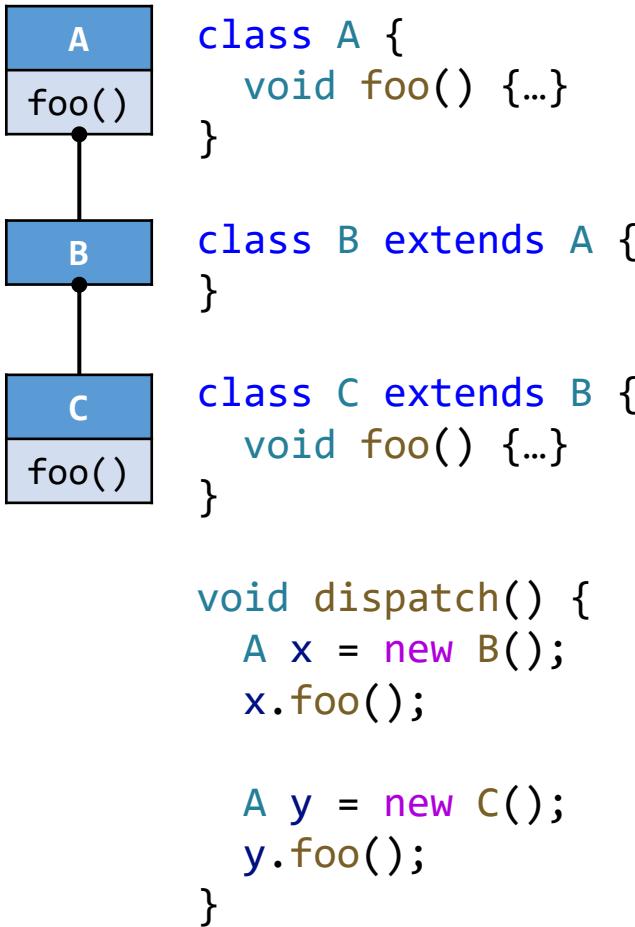
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$\text{Dispatch}(C, A.\text{foo}()) = ?$

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Class Hierarchy Analysis* (CHA)

- Require the class hierarchy information (inheritance structure) of the whole program
- Resolve a virtual call based on the **declared type of receiver variable** of the call site

```
A a = ...  
a.foo();
```

* Jeffrey Dean, David Grove, Craig Chambers, “*Optimization of Object-Oriented Programs Using Static Class Hierarchy Analysis*”. ECOOP 1995.

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- Assume the receiver variable **a** may point to objects of class **A** or all subclasses of **A**
 - Resolve target methods by looking up the **class hierarchy** of class **A**

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Call Resolution of CHA

We define function **Resolve**(*cs*) to resolve possible target methods of a call site *cs* by CHA

Resolve(*cs*)

$T = \{\}$

m = method signature at *cs*

if *cs* is a static call **then**

$T = \{ m \}$

if *cs* is special call **then**

c^m = class type of *m*

$T = \{ \text{Dispatch}(c^m, m) \}$

if *cs* is a virtual call **then**

c = declared type of receiver variable at *cs*

foreach *c'* that is a subclass of *c* or *c* itself **do**

add **Dispatch**(*c'*, *m*) to *T*

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class C {
    static T foo(P p, Q q)
    ...
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C.foo(x, y); ←

cs C.foo(x, y);

m <C: T foo(P,Q)>

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        ...  
        super.foo(p, q); ←  
    }  
}
```

cs super.foo(p, q);
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c^m B

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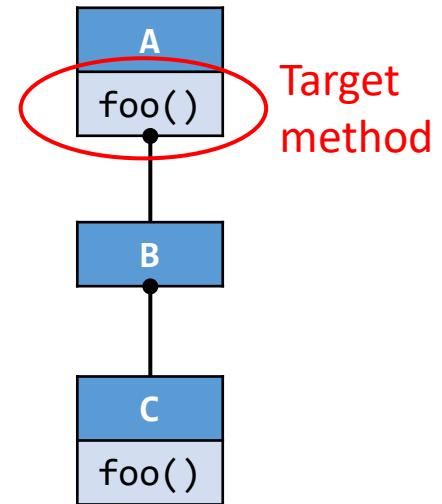
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```
class C extends B {  
    T foo(P p, Q q) {  
        ...  
        this.bar(); ←  
    }  
    private T bar()  
}  
C c = new C(); ←
```

Special call

- Private instance method
- Constructor
- Superclass instance method

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return *T*

```
class A {  
    T foo(P p, Q q) {...}  
}  
A a = ...  
a.foo(x, y); ←
```

```
cs a.foo(x, y);  
m <A: T foo(P,Q)>  
c A
```

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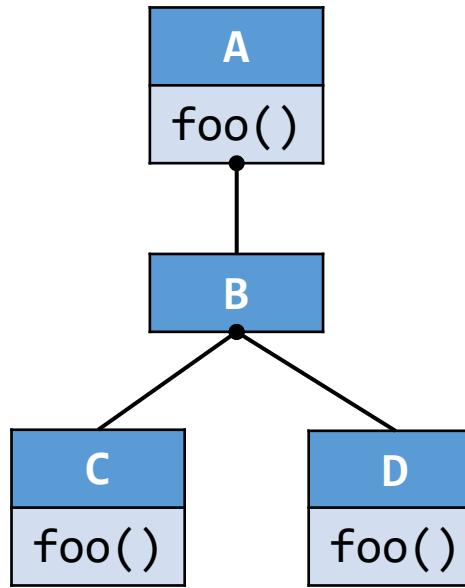
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class A {  
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}  
A a = ...  
a.foo(x, y); ←
```

```
cs a.foo(x, y);  
m <A: T foo(P,Q)>  
c A
```

Subclasses includes all **direct** and **indirect** subclasses of *c*

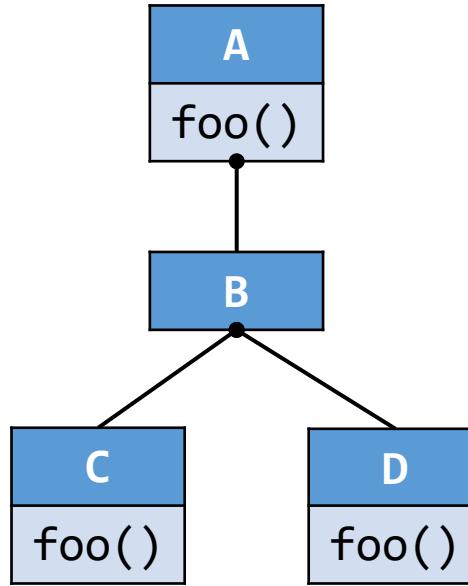
CHA: An Example

```
class A {  
    void foo() {...}  
}  
class B extends A {}  
  
class C extends B {  
    void foo() {...}  
}  
class D extends B {  
    void foo() {...}  
}  
  
void resolve() {  
    C c = ...  
    c.foo();  
  
    A a = ...  
    a.foo();  
  
    B b = ...  
    b.foo();  
}
```



CHA: An Example

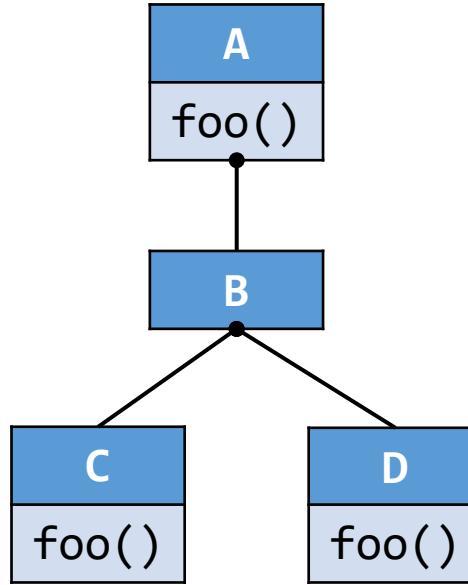
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class A {  
    void foo() {...}  
}  
class B extends A {}  
  
class C extends B {  
    void foo() {...}  
}  
class D extends B {  
    void foo() {...}  
}  
  
void resolve() {  
    C c = ...  
    c.foo(); ?  
    A a = ...  
    a.foo();  
  
    B b = ...  
    b.foo();  
}
```



Resolve(c.foo()) = ?

CHA: An Example

```
class A {  
    void foo() {...}  
}  
class B extends A {}  
  
class C extends B {  
    void foo() {...}  
}  
class D extends B {  
    void foo() {...}  
}  
  
void resolve() {  
    C c = ...  
    c.foo();  
  
    A a = ...  
    a.foo(); ?  
  
    B b = ...  
    b.foo();  
}
```

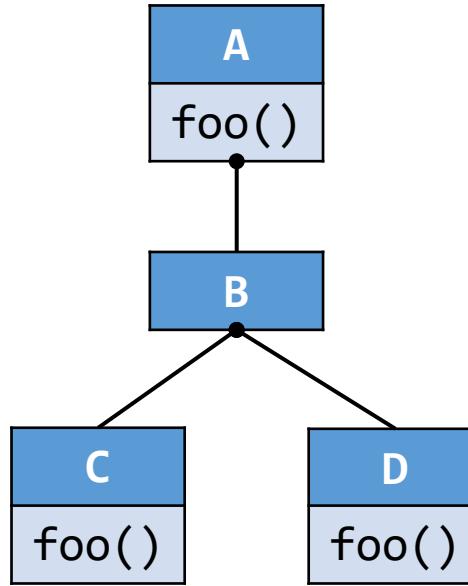


Resolve(c.foo()) = {C.foo()}

Resolve(a.foo()) = ?

CHA: An Example

```
class A {  
    void foo() {...}  
}  
class B extends A {}  
  
class C extends B {  
    void foo() {...}  
}  
class D extends B {  
    void foo() {...}  
}  
  
void resolve() {  
    C c = ...  
    c.foo();  
  
    A a = ...  
    a.foo();  
  
    B b = ...  
    b.foo(); ?  
}
```



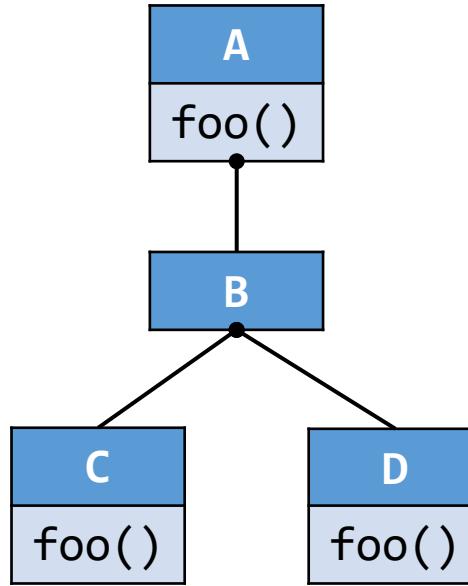
Resolve(c.foo()) = {C.foo()}

Resolve(a.foo()) = {A.foo(), C.foo(), D.foo()}

Resolve(b.foo()) = ?

CHA: An Example

```
class A {  
    void foo() {...}  
}  
class B extends A {}  
  
class C extends B {  
    void foo() {...}  
}  
class D extends B {  
    void foo() {...}  
}  
  
void resolve() {  
    C c = ...  
    c.foo();  
  
    A a = ...  
    a.foo();  
  
    B b = ...  
    b.foo();  
}
```



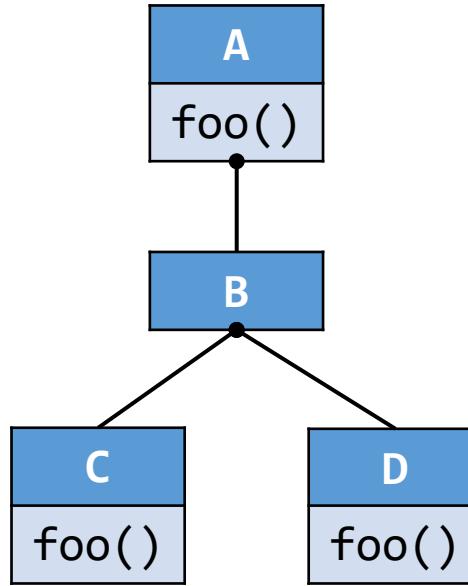
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CHA: An Example

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}  
class B extends A {}  
  
class C extends B {  
    void foo() {...}  
}  
class D extends B {  
    void foo() {...}  
}  
  
void resolve() {  
    C c = ...  
    c.foo();  
  
    A a = ...  
    a.foo();  
  
    → B b = new B();  
    b.foo(); ?  
}
```



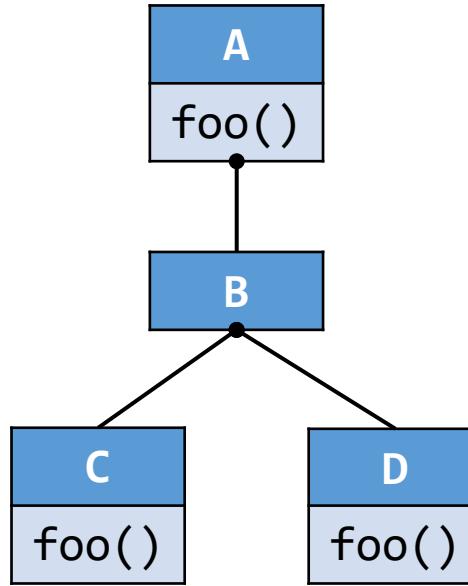
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class B extends A {}  
  
class C extends B {  
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}  
class D extends B {  
    void foo() {...}  
}  
  
void resolve() {  
    C c = ...  
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    A a = ...  
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Features of CHA

- Advantage: fast
 - Only consider the declared type of receiver variable at the call-site, and its inheritance hierarchy
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Common usage: IDE

CHA in IDE (IntelliJ IDEA)

The screenshot shows the IntelliJ IDEA interface with the code editor and the Call Hierarchy tool window.

Code Editor (TestCHA.java):

```
1 public class TestCHA {  
2     void test() {  
3         B b = new B();  
4         b.foo();  
5     }  
6 }  
7 class A {  
8     void foo() {}  
9 }  
10 class B extends A {}  
11 class C extends B {  
12     void foo() {}  
13 }  
14 class D extends B {  
15     void foo() {}  
16 }
```

Call Hierarchy Tool Window:

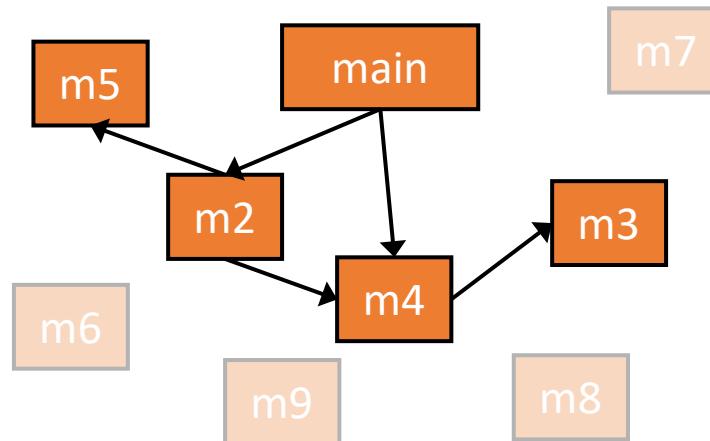
Hierarchy: Callees of foo

				Scope:	All
*	m	o	A.foo()		
m	o	C.foo()			
m	o	D.foo()			

Call Graph Construction

Build call graph for whole program via CHA

- Start from entry methods (focus on main method)
- For each reachable method m , resolve target methods for each call site cs in m via CHA (**Resolve**(cs))
- Repeat until no new method is discovered



Call Graph Construction: Algorithm

BuildCallGraph(m^{entry})

$WL = [m^{entry}]$, $CG = \{\}$, $RM = \{\}$

while WL is not empty **do**

 remove m from WL

if $m \notin RM$ **then**

 add m to RM

foreach call site cs in m **do**

$T = \text{Resolve}(cs)$

foreach target method m' in T **do**

 add $cs \rightarrow m'$ to CG

 add m' to WL

return CG

WL Work list, containing the methods to be processed

CG Call graph, a set of call edges

RM A set of reachable methods

Call Graph Construction: Algorithm

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$WL = [m^{entry}]$, $CG = \{\}$, $RM = \{\}$ —— Initialize the algorithm

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Resolve target methods via CHA

Add call edges to call graph

May discover new method,
add it to work list

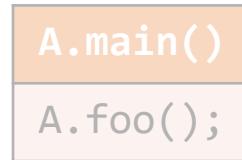
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CG Call graph, a set of call edges

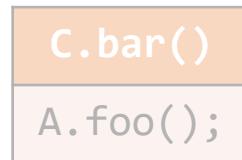
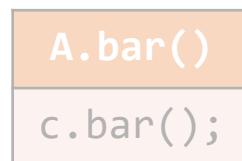
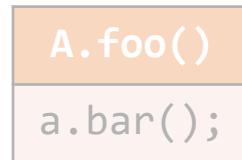
RM A set of reachable methods

Call Graph Construction: An Example

```
class A {  
    static void main() {  
        A.foo();  
    }  
    static void foo() {  
        A a = new A();  
        a.bar();  
    }  
    void bar() {  
        C c = new C();  
        c.bar();  
    }  
}  
  
class B extends A {  
    void bar() {} }  
  
class C extends A {  
    void bar() {  
        if (...) A.foo();  
    }  
    void m() {}  
}
```



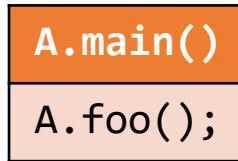
Initialization with main method



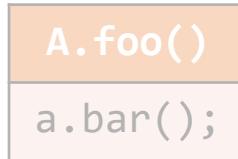
$$WL = [A.\text{main}()]$$

Call Graph Construction: An Example

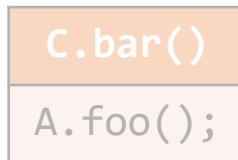
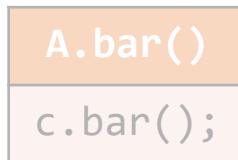
```
class A {  
    static void main() {  
        A.foo(); ←  
    }  
  
    static void foo() {  
        A a = new A();  
        a.bar();  
    }  
  
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    }  
}  
  
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    void bar() {  
        if (...) A.foo();  
    }  
  
    void m() {}  
}
```



$WL = []$

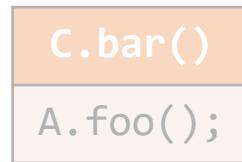
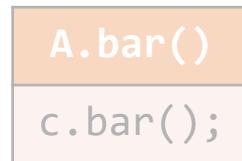
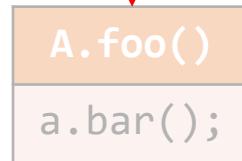
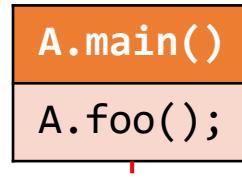


Resolve(A.foo()) = ?



Call Graph Construction: An Example

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class A {  
    static void main() {  
        A.foo(); ←  
    }  
  
    static void foo() {  
        A a = new A();  
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    }  
  
    void bar() {  
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    }  
}  
  
class B extends A {  
    void bar() {} }  
class C extends A {  
    void bar() {  
        if (...) A.foo();  
    }  
  
    void m() {}  
}
```

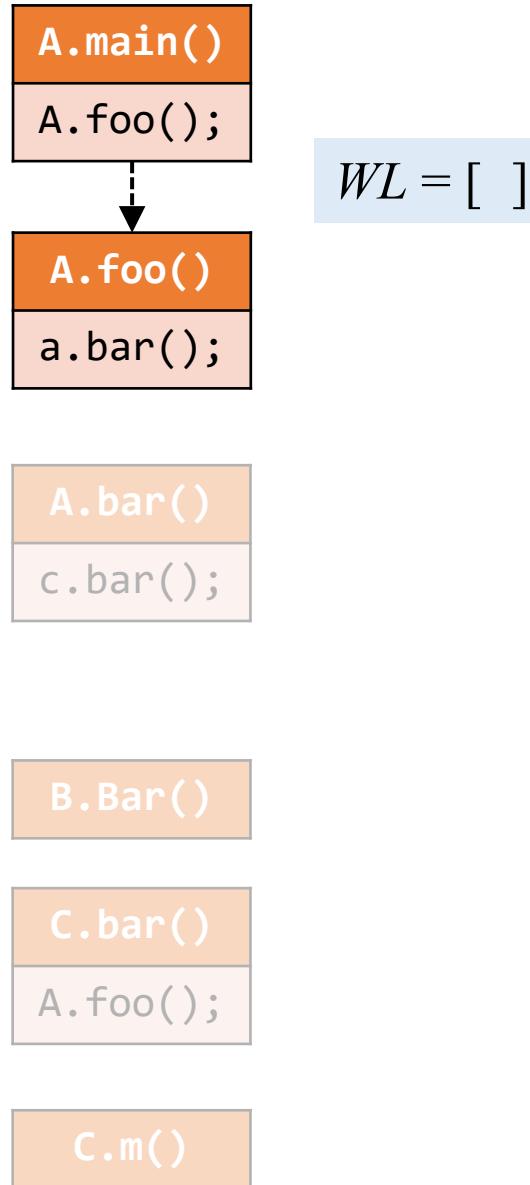


$$WL = [A.foo()]$$

$$\text{Resolve}(A.foo()) = \{ A.foo() \}$$

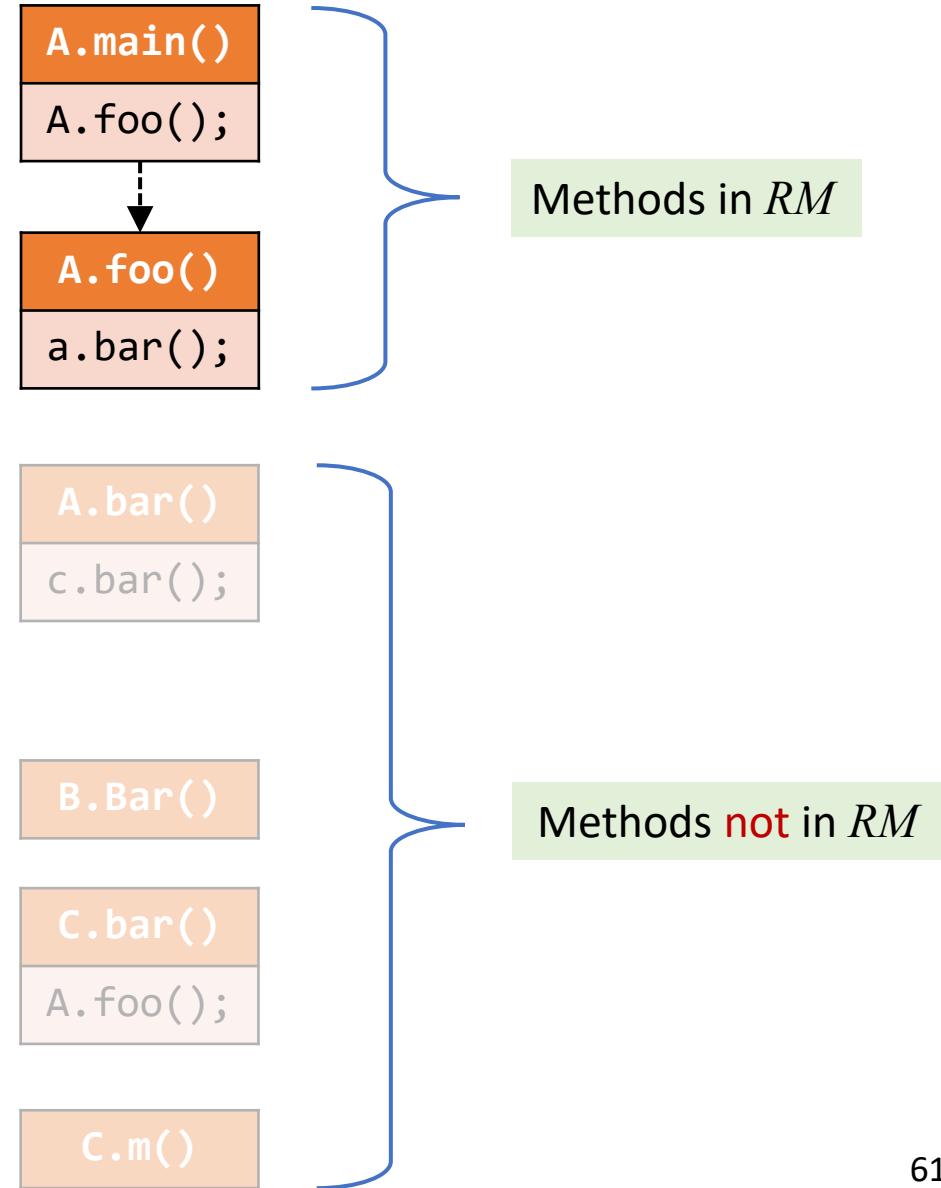
Call Graph Construction: An Example

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```



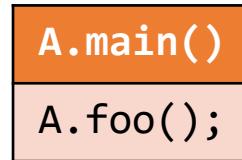
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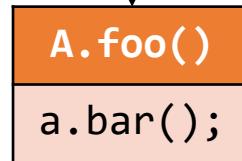


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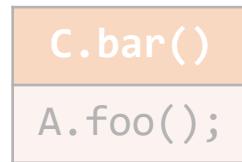
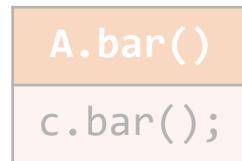
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class B extends A {  
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    void bar() {  
        if (...) A.foo();  
    }  
    void m() {}  
}
```



$WL = []$

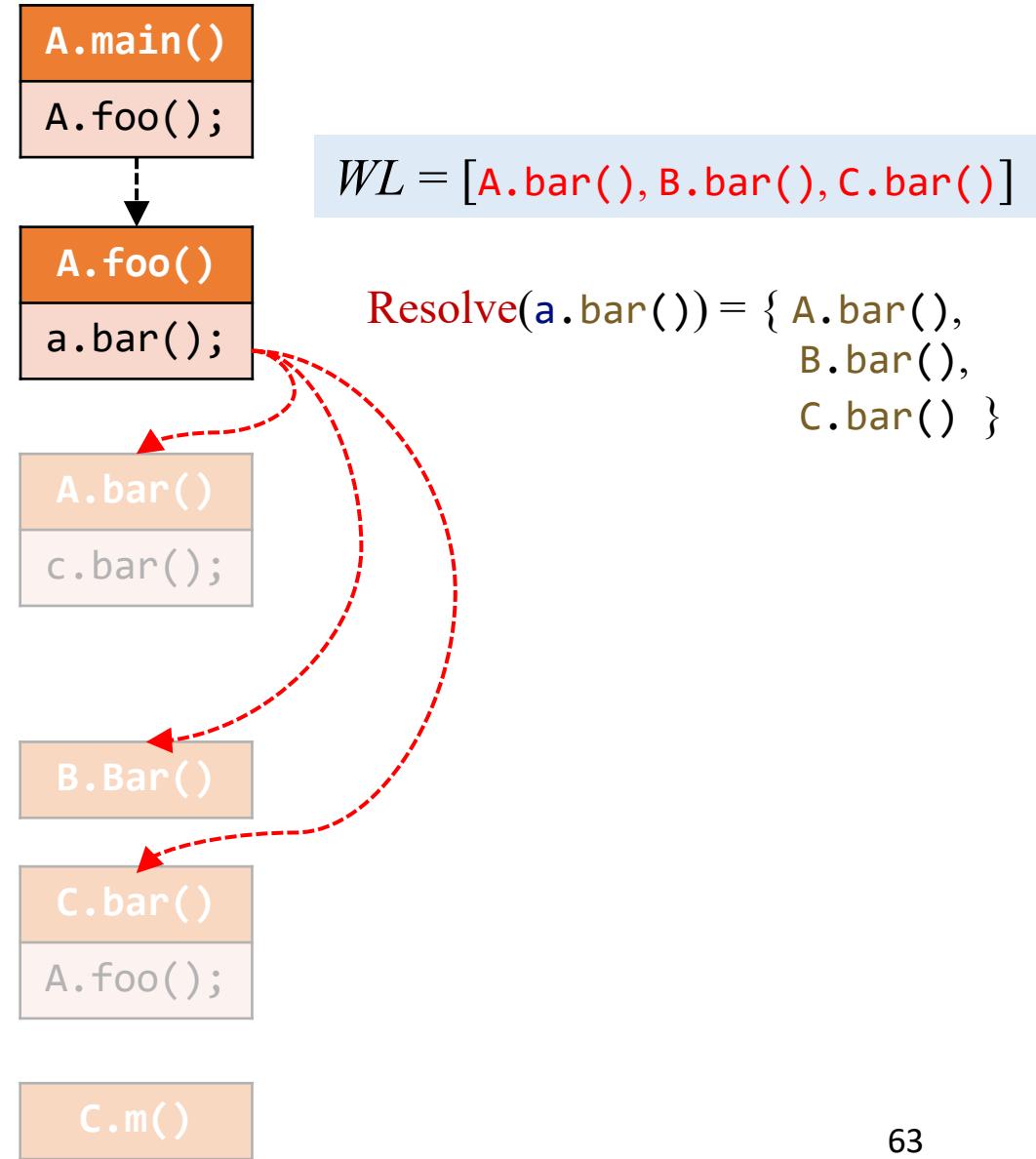


Resolve(a.bar()) = ?



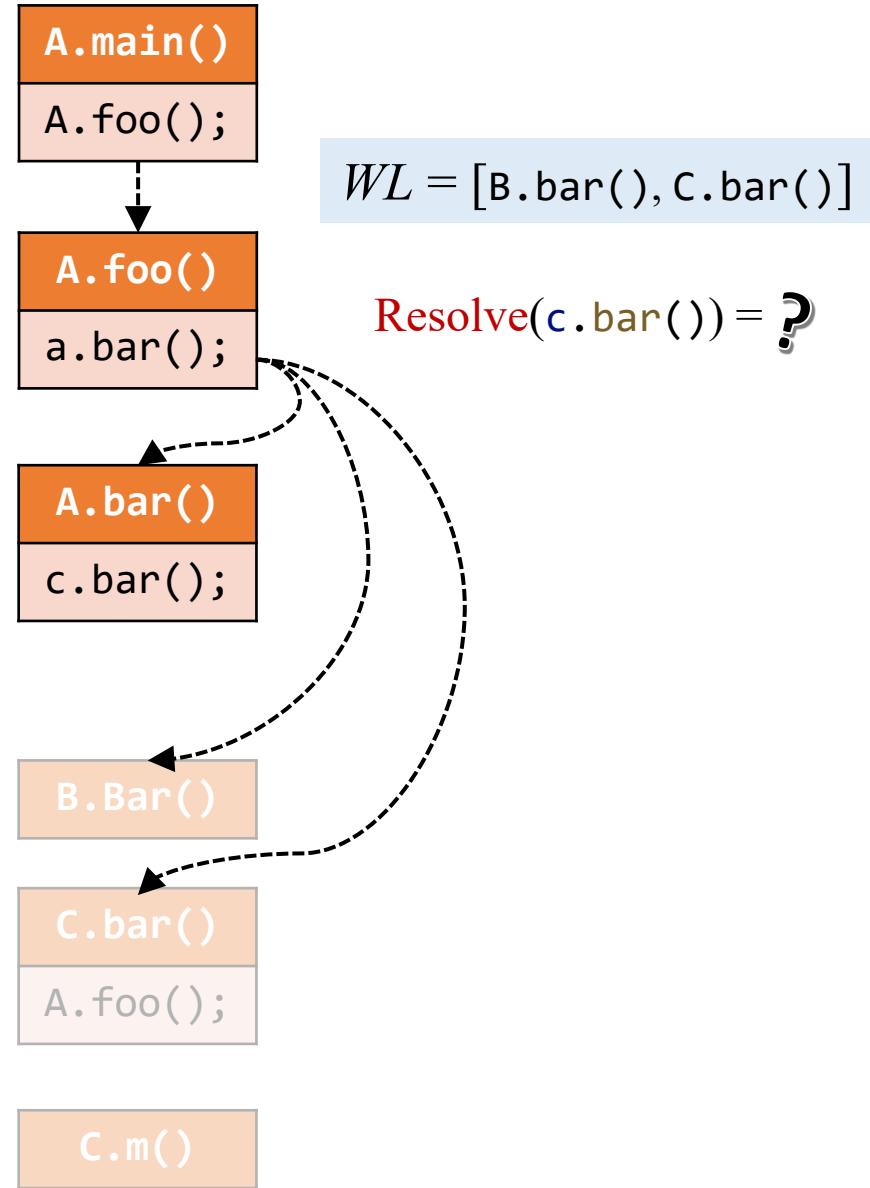
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class A {  
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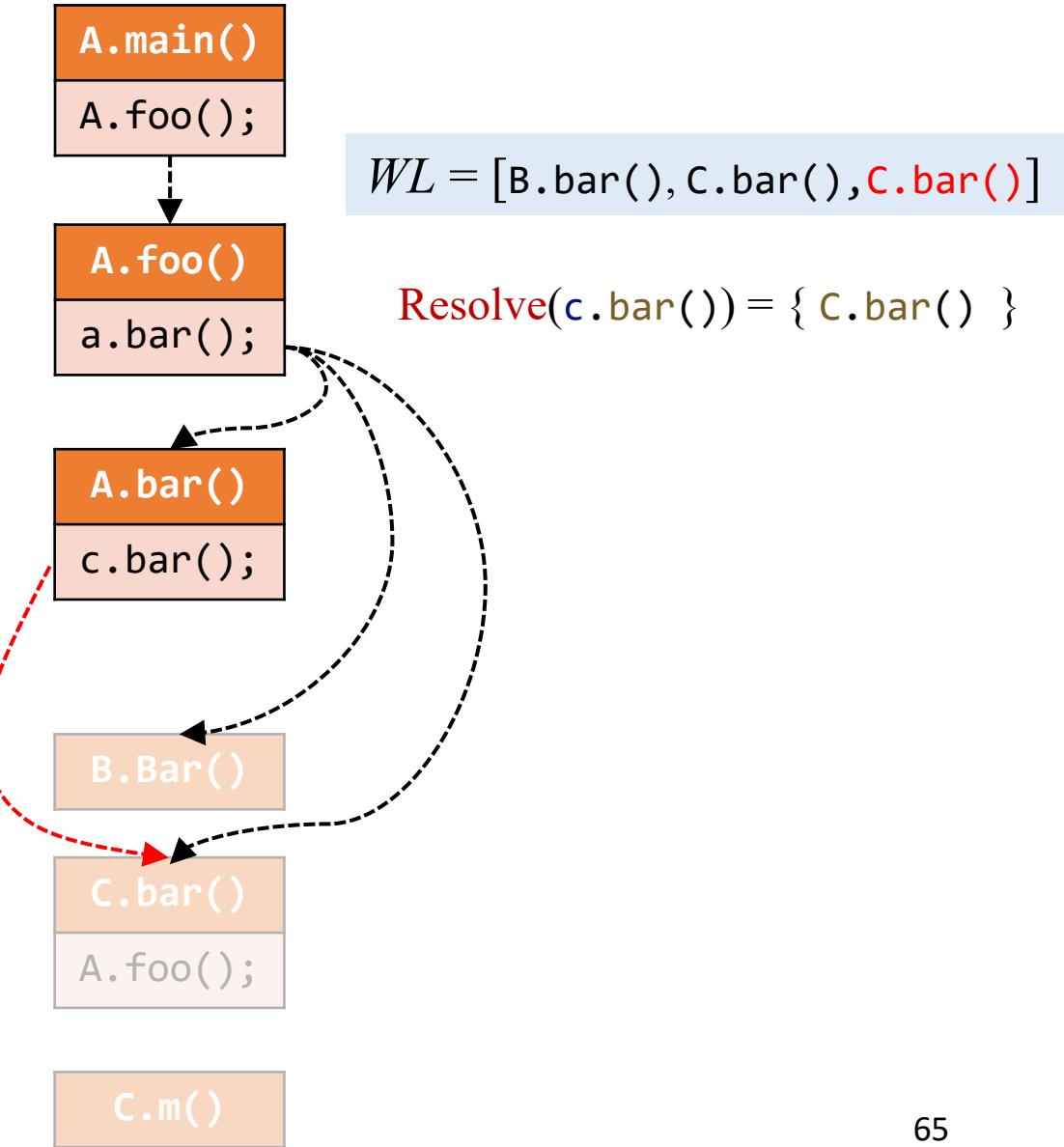
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        if (...) A.foo();  
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}
```



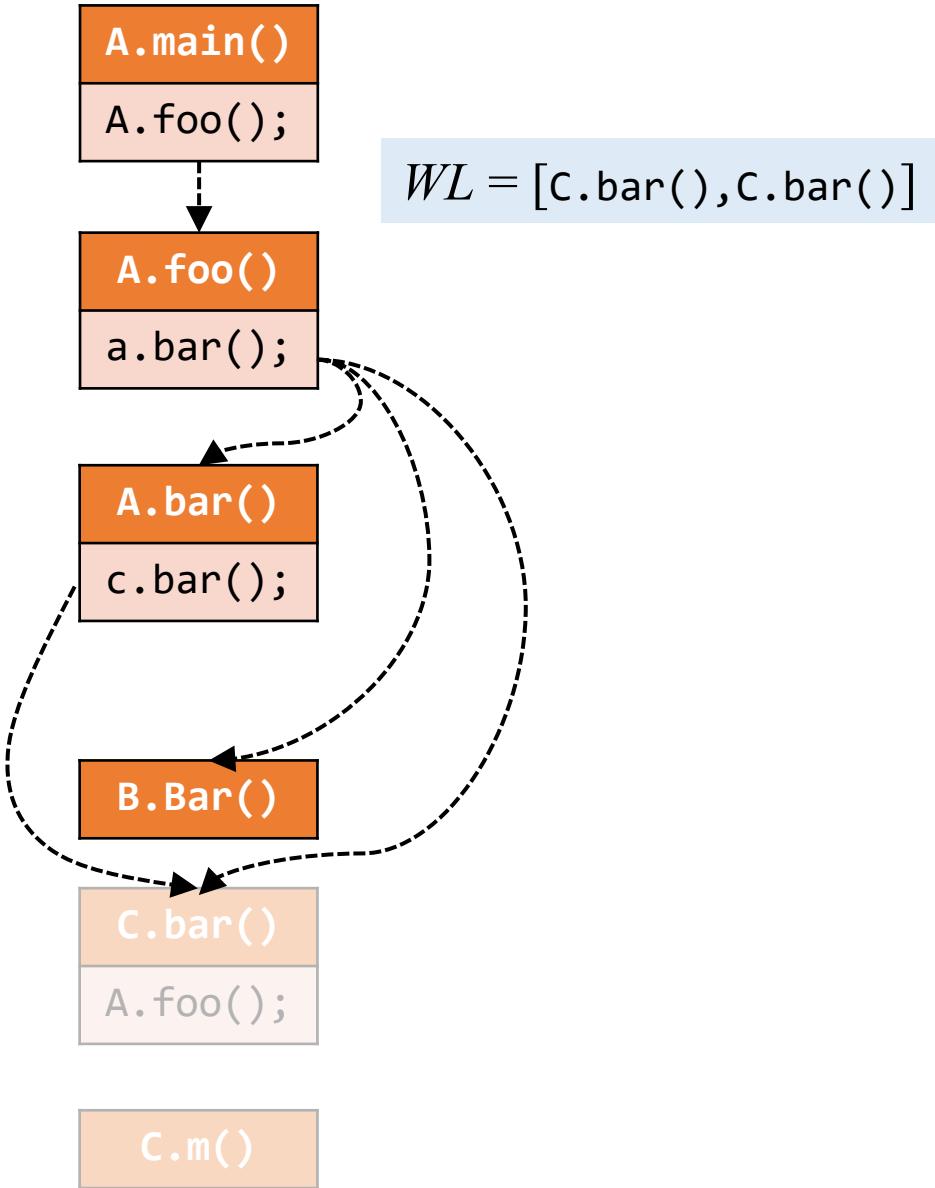
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```



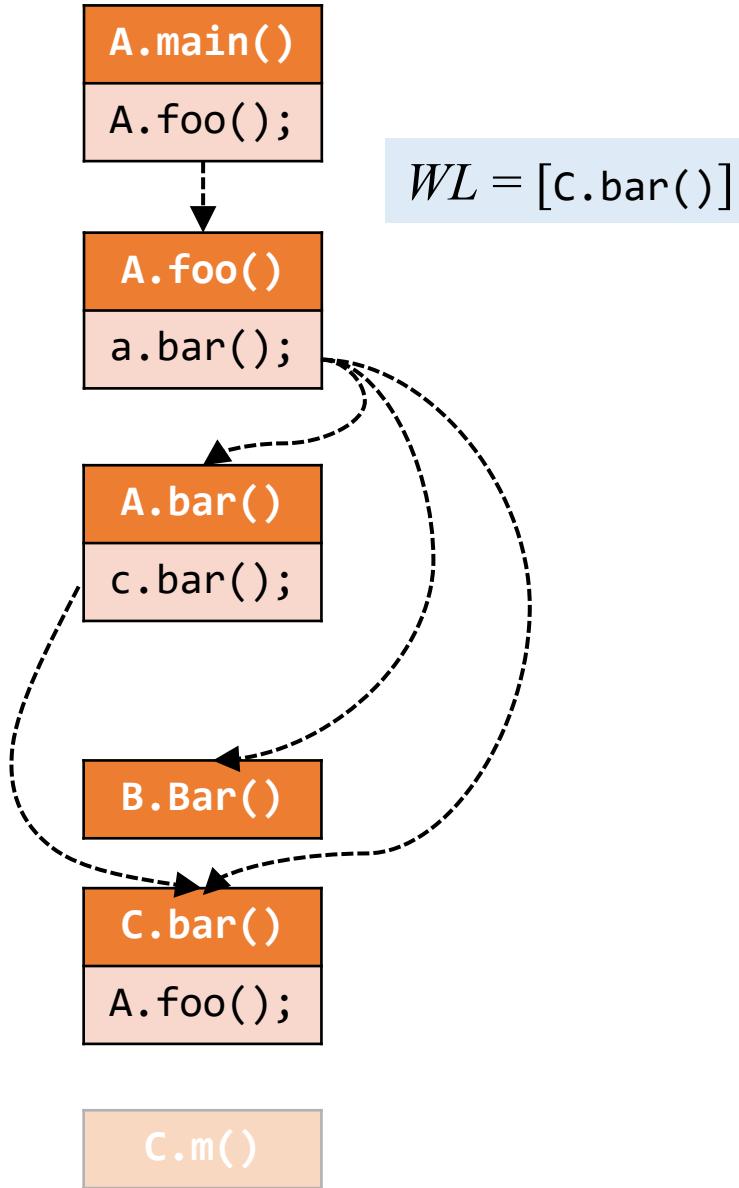
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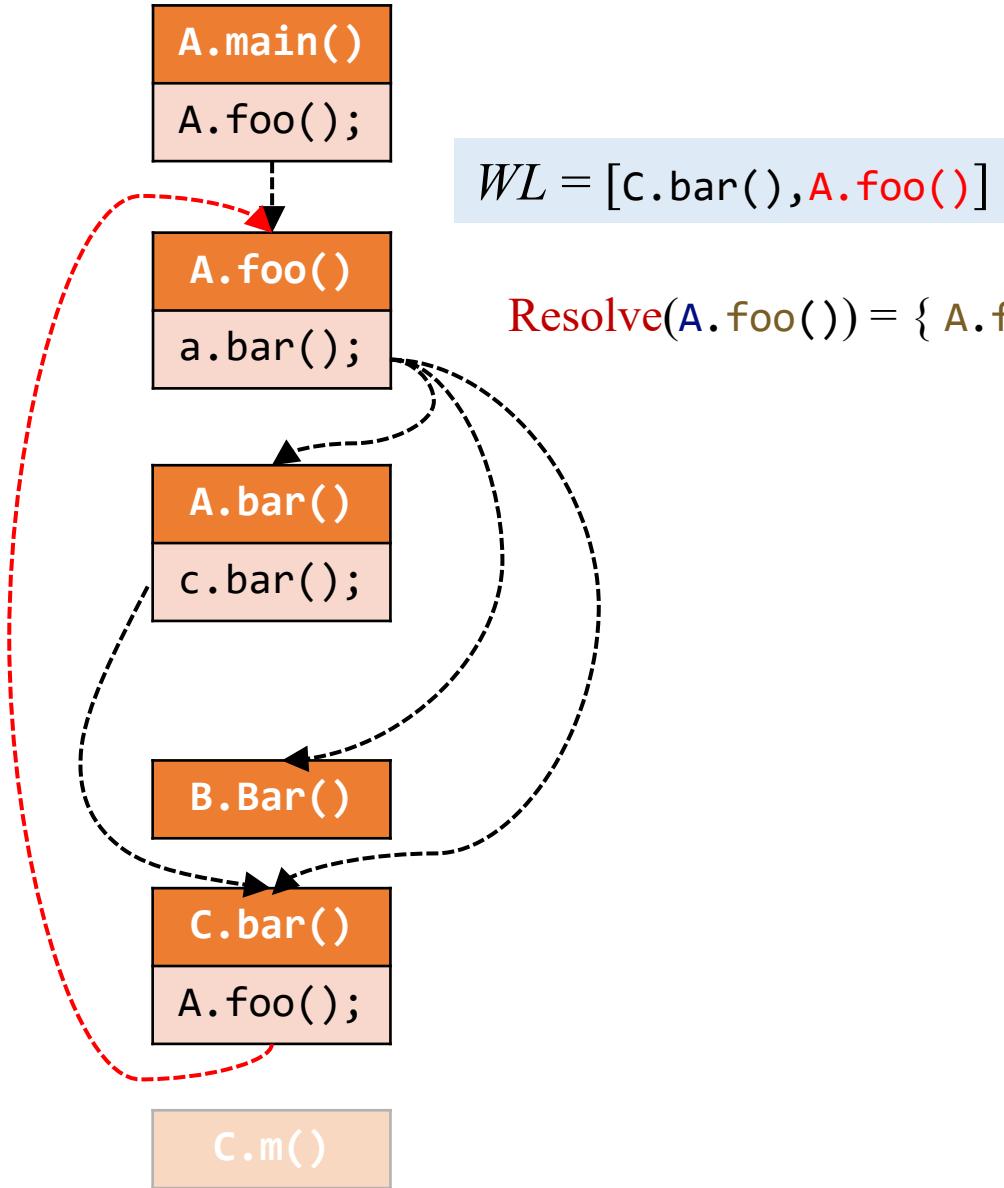
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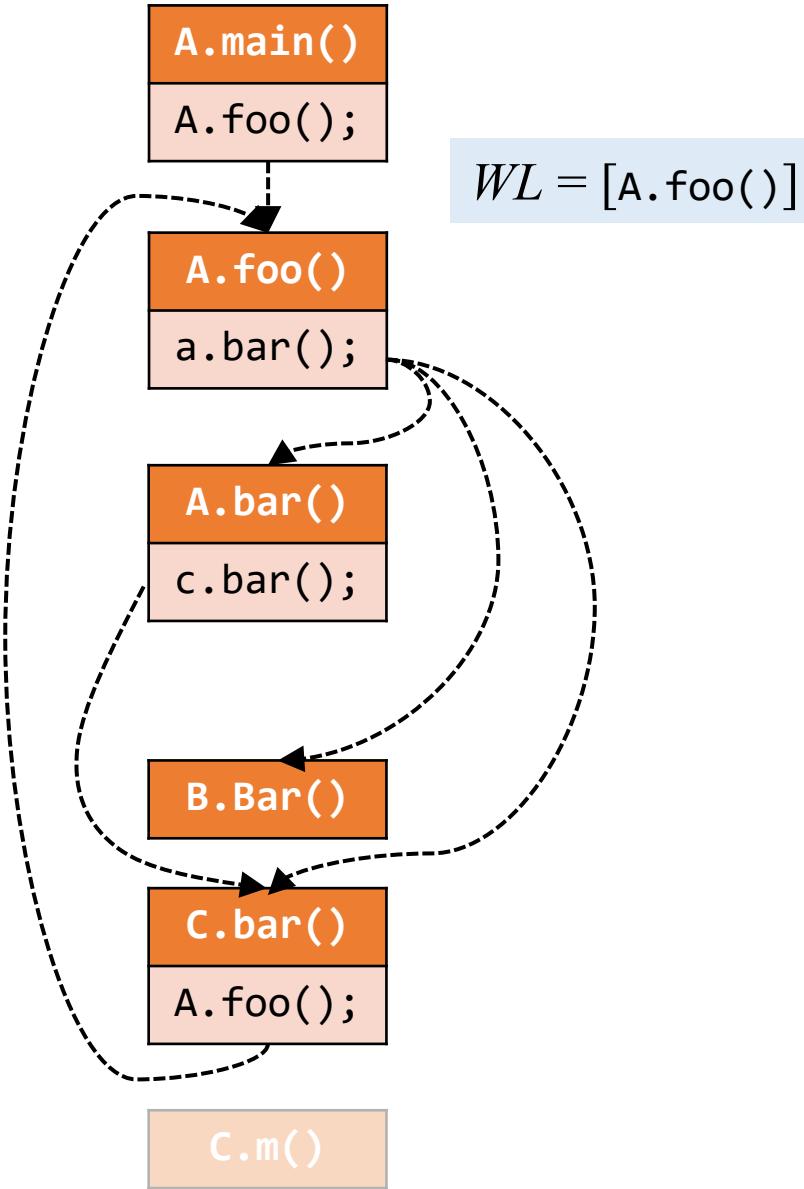
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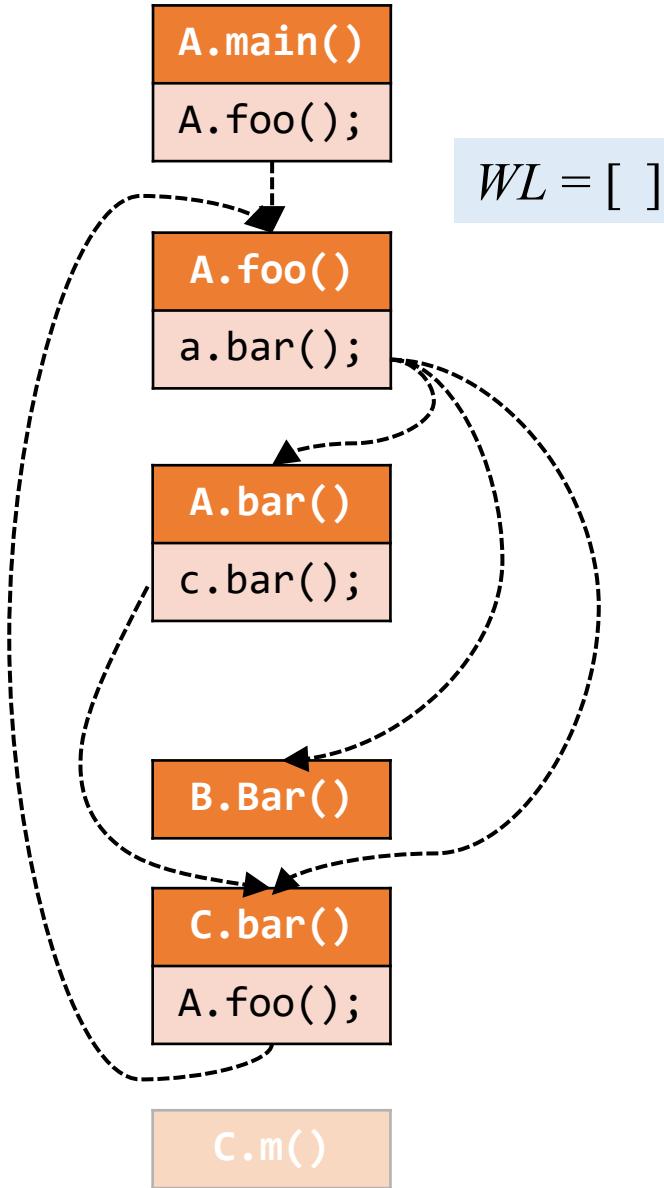
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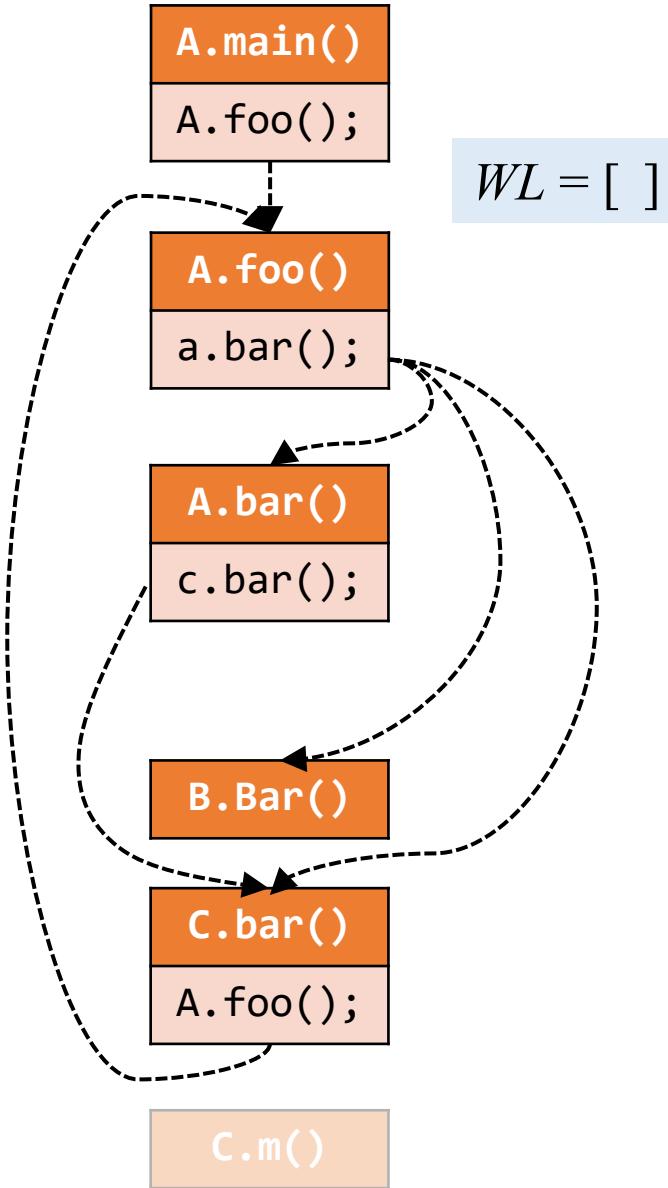
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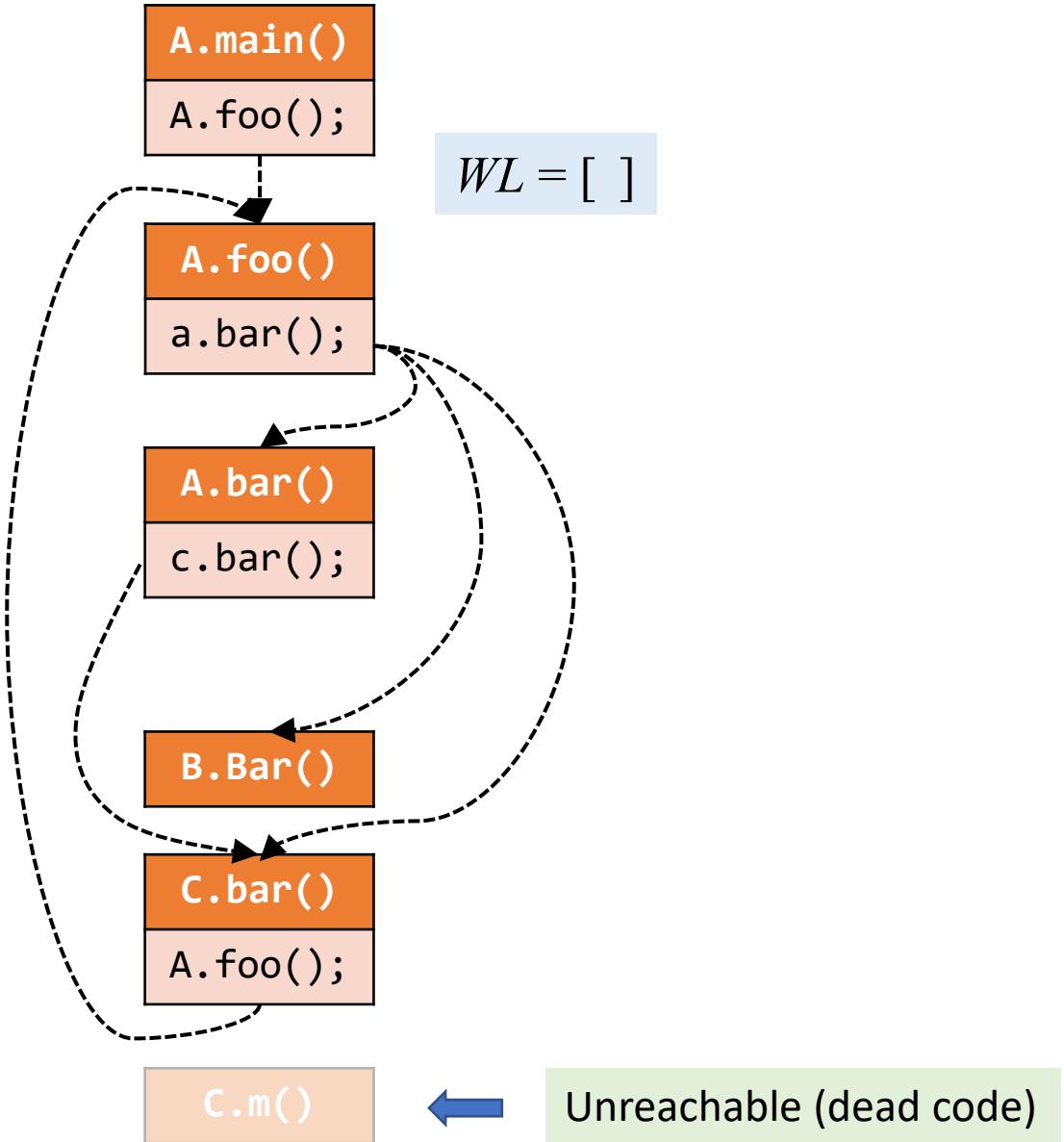
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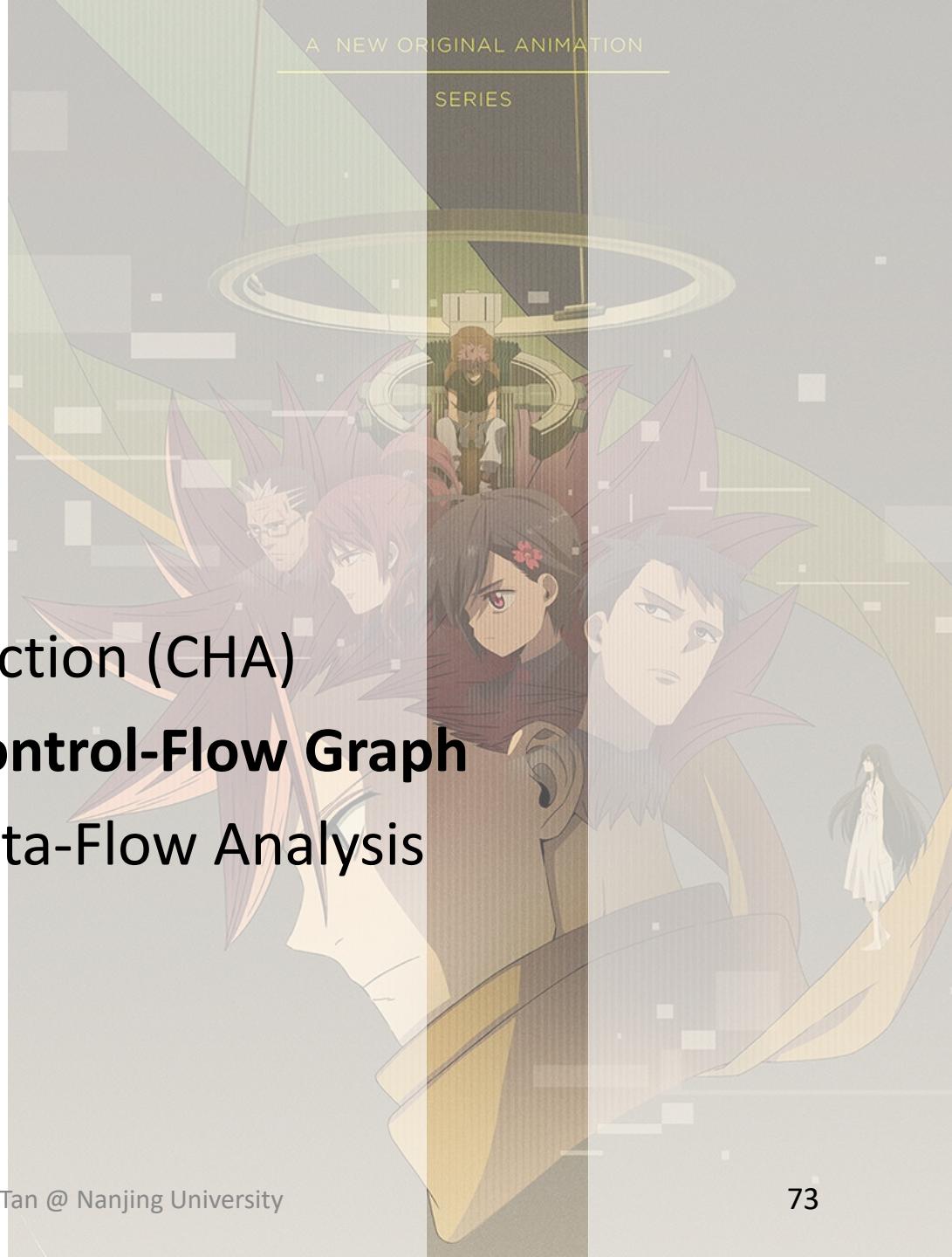
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```



Contents

1. Motivation
2. Call Graph Construction (CHA)
3. **Interprocedural Control-Flow Graph**
4. Interprocedural Data-Flow Analysis



Interprocedural Control-Flow Graph

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- ICFG represents structure of the whole program
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 - **Return edges**: from exit nodes of the callees to the statements following their call sites (i.e., return sites)

```
void foo() {  
    bar(...); // call site  
    int n = 3; // return site  
}
```

Interprocedural Control-Flow Graph

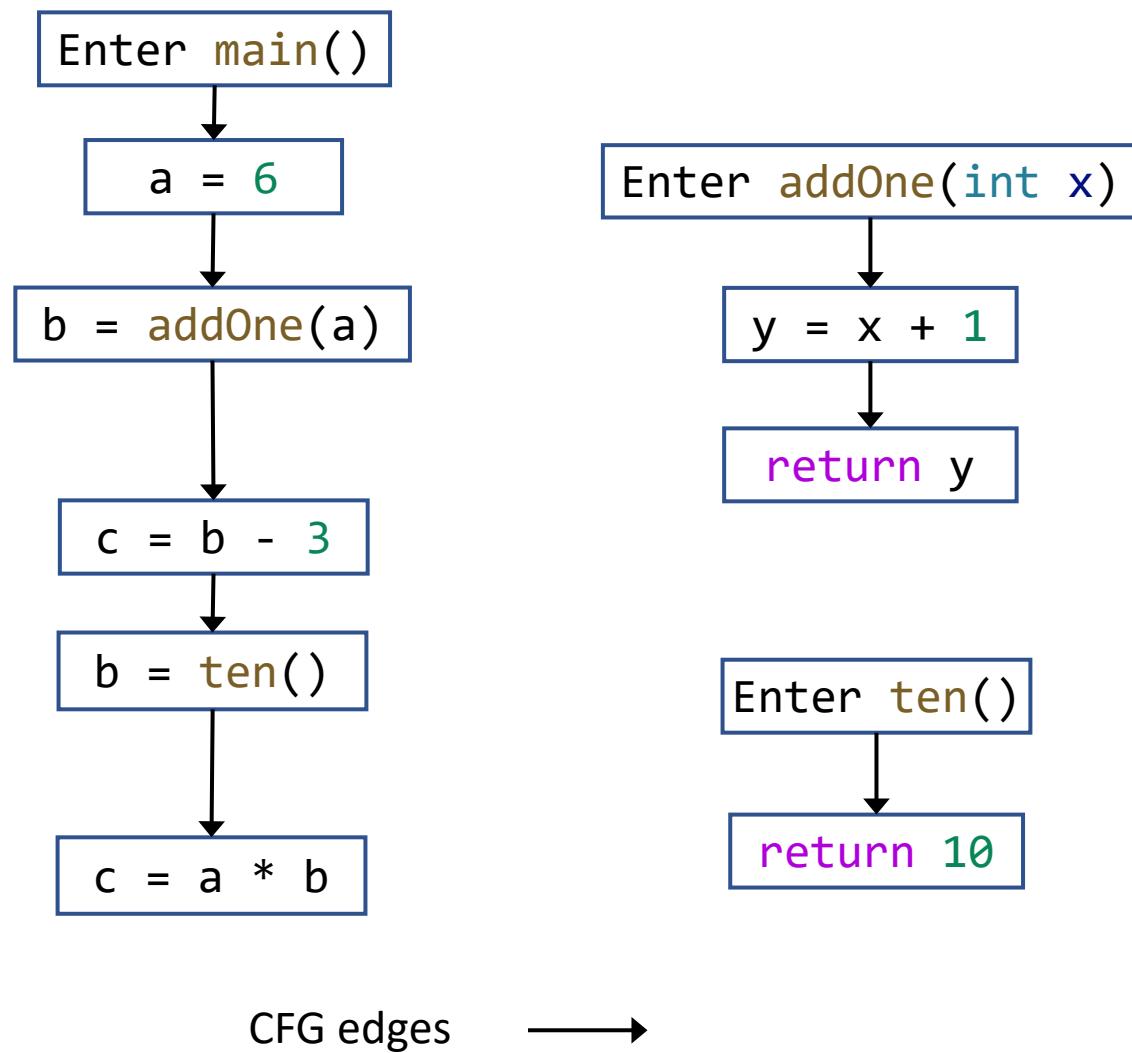
- CFG represents structure of an individual method
- ICFG represents structure of the whole program
 - With ICFG, we can perform interprocedural analysis
- An ICFG of a program consists of CFGs of the methods in the program, plus **two kinds of additional edges**:
 - **Call edges**: from call sites to the entry nodes of their callees
 - **Return edges**: from exit nodes of the callees to the statements following their call sites (i.e., return sites)

ICFG = CFGs + call & return edges

The information for connecting these two kinds of edges comes from **call graph**

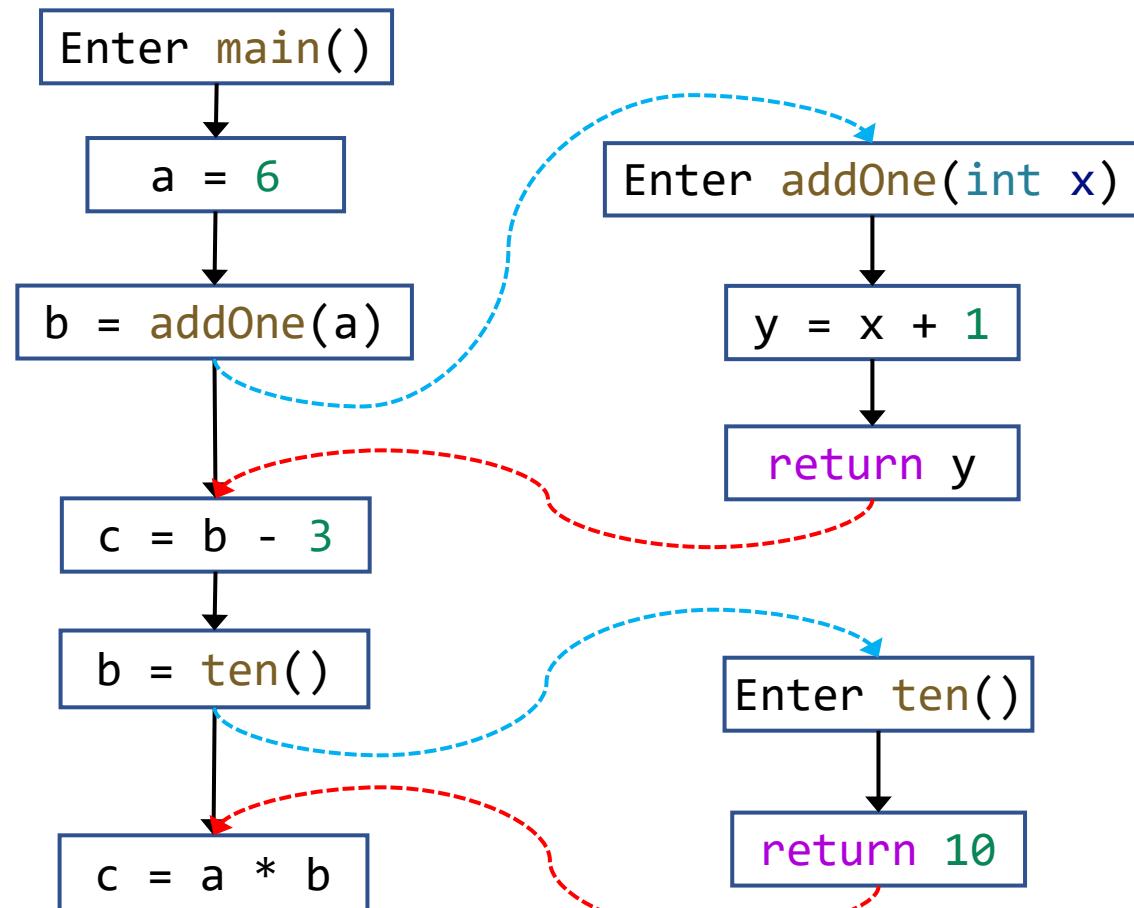
ICFG: An Example

```
static void main() {  
    int a, b, c;  
    a = 6;  
    b = addOne(a);  
    c = b - 3;  
    b = ten();  
    c = a * b;  
}  
  
int addOne(int x) {  
    int y = x + 1;  
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ICFG: An Example

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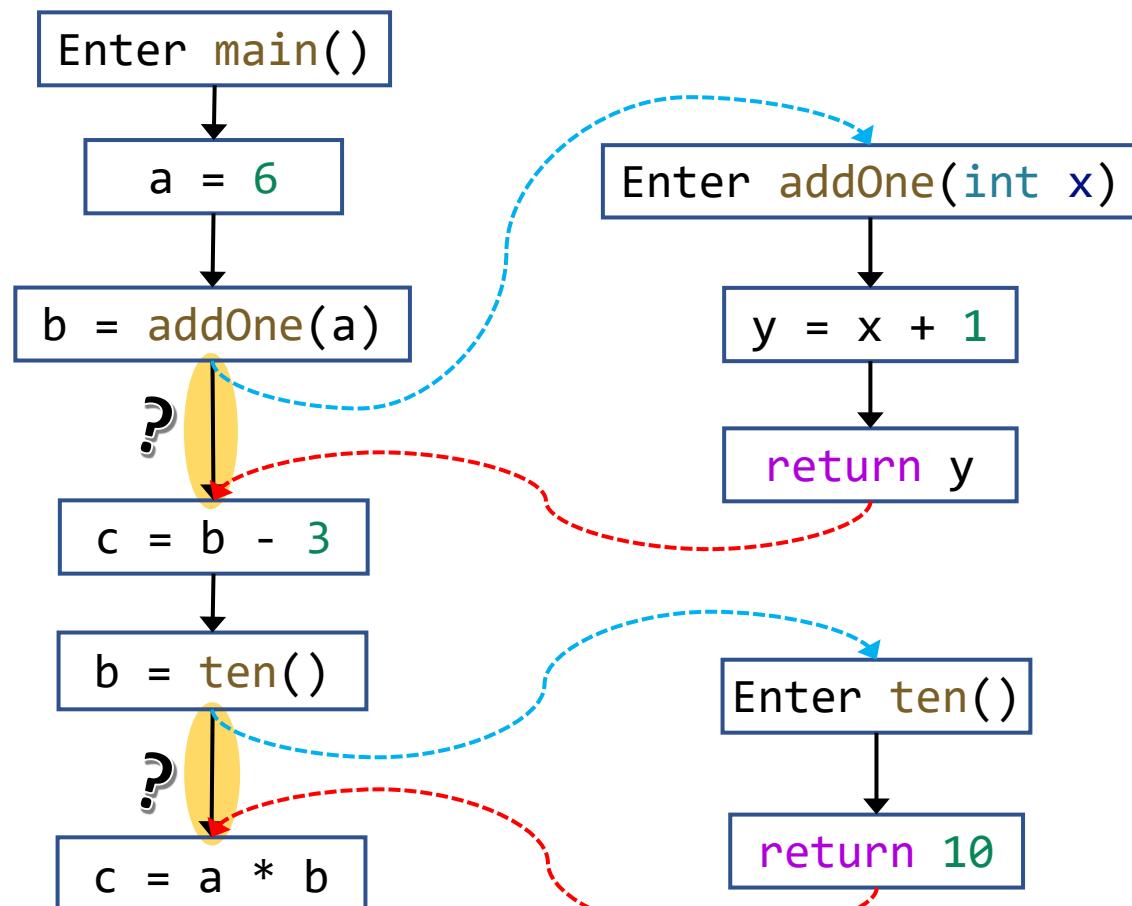


CFG edges →
Call edges →
Return edges →

ICFG = CFGs + call & return edges

ICFG: An Example

```
static void main() {  
    int a, b, c;  
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ICFG = CFGs + call & return edges

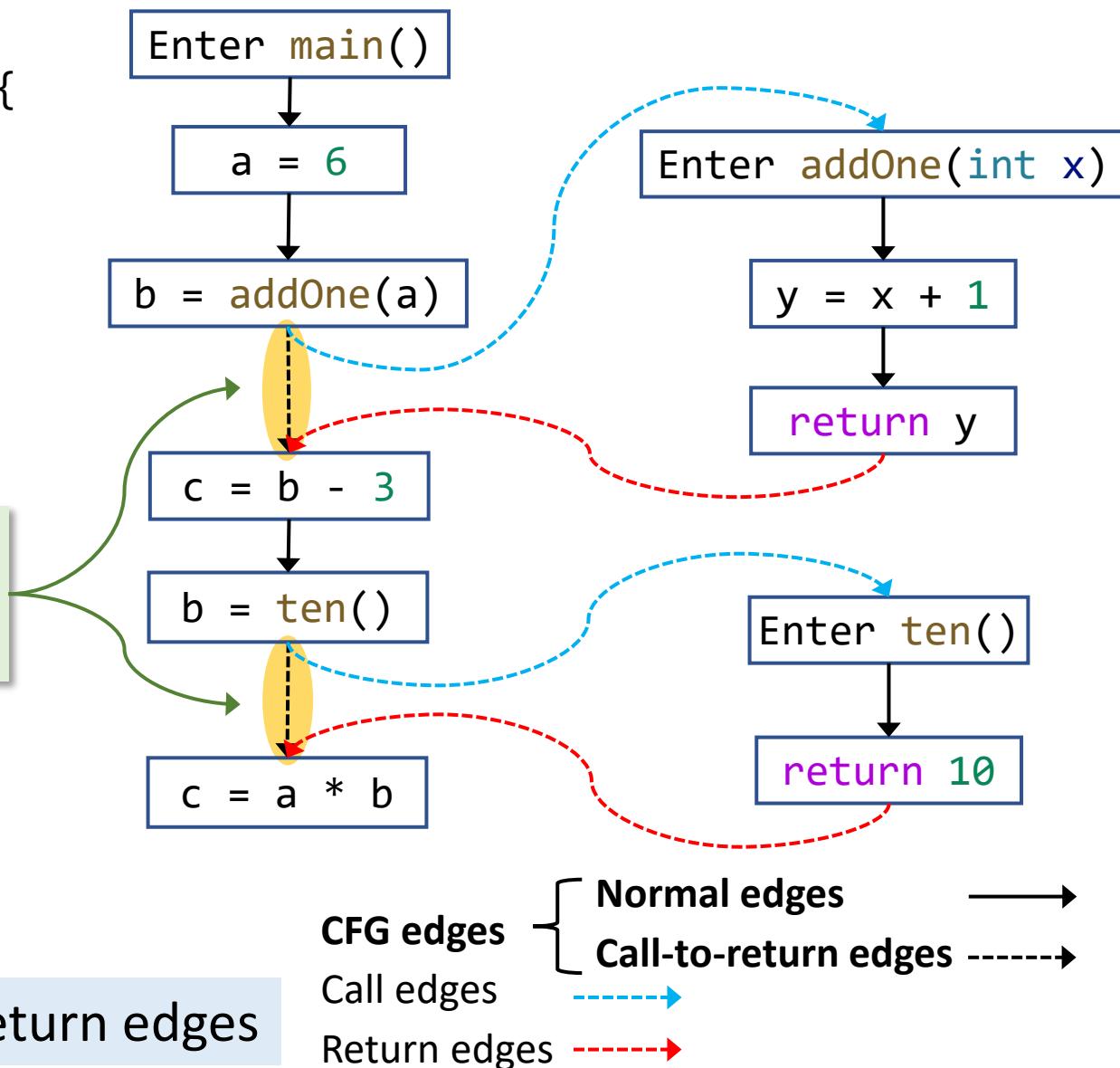
CFG edges →
Call edges →
Return edges →

ICFG: An Example

```
static void main() {  
    int a, b, c;  
    a = 6;  
    b = addOne(a);  
    c = b - 3;  
    b = ten();  
    c = a * b;  
}
```

Such edges (from call site to return site) are called
call-to-return edges

```
int ten() {  
    return 10;  
}
```



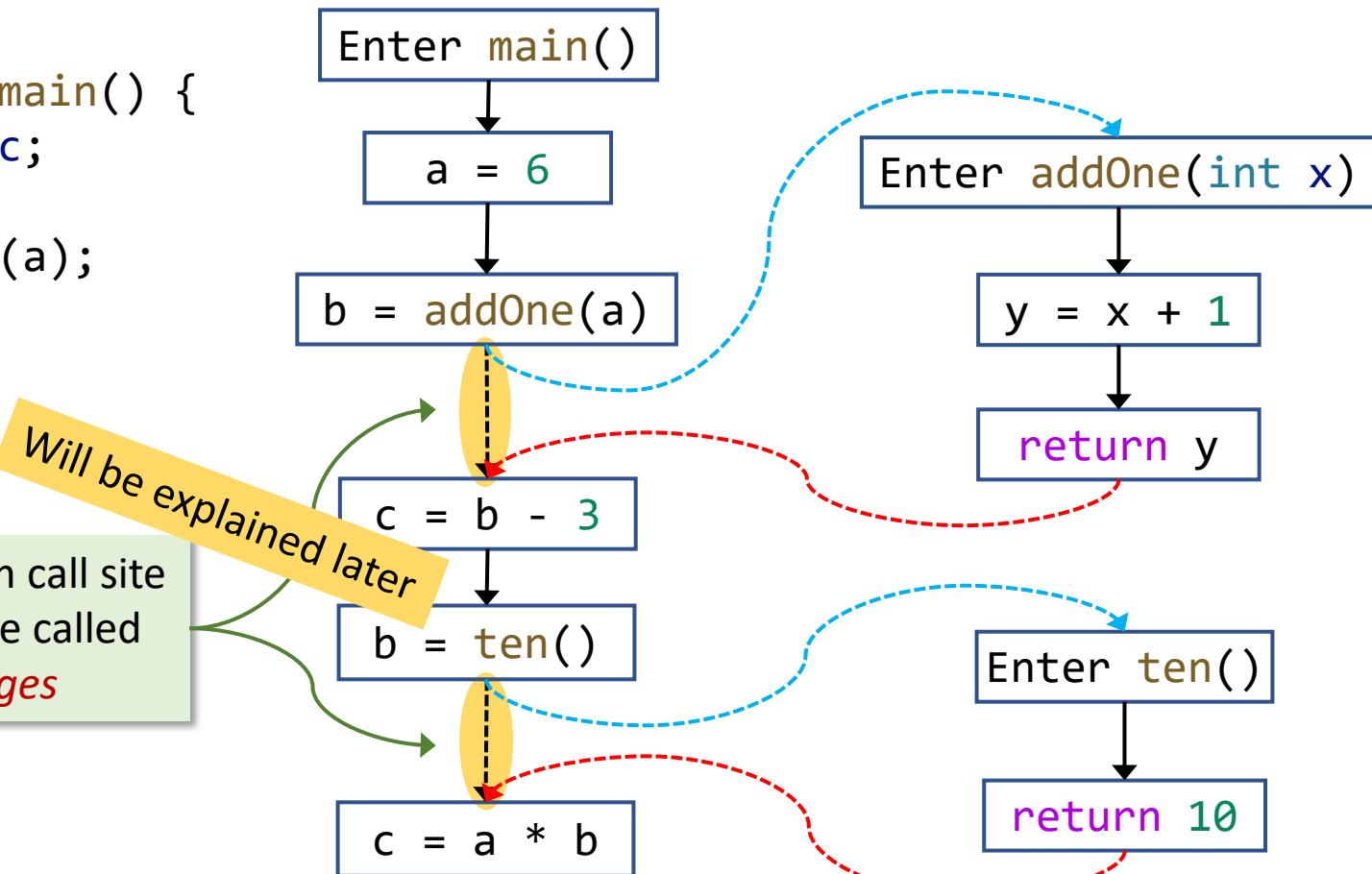
ICFG = CFGs + call & return edges

ICFG: An Example

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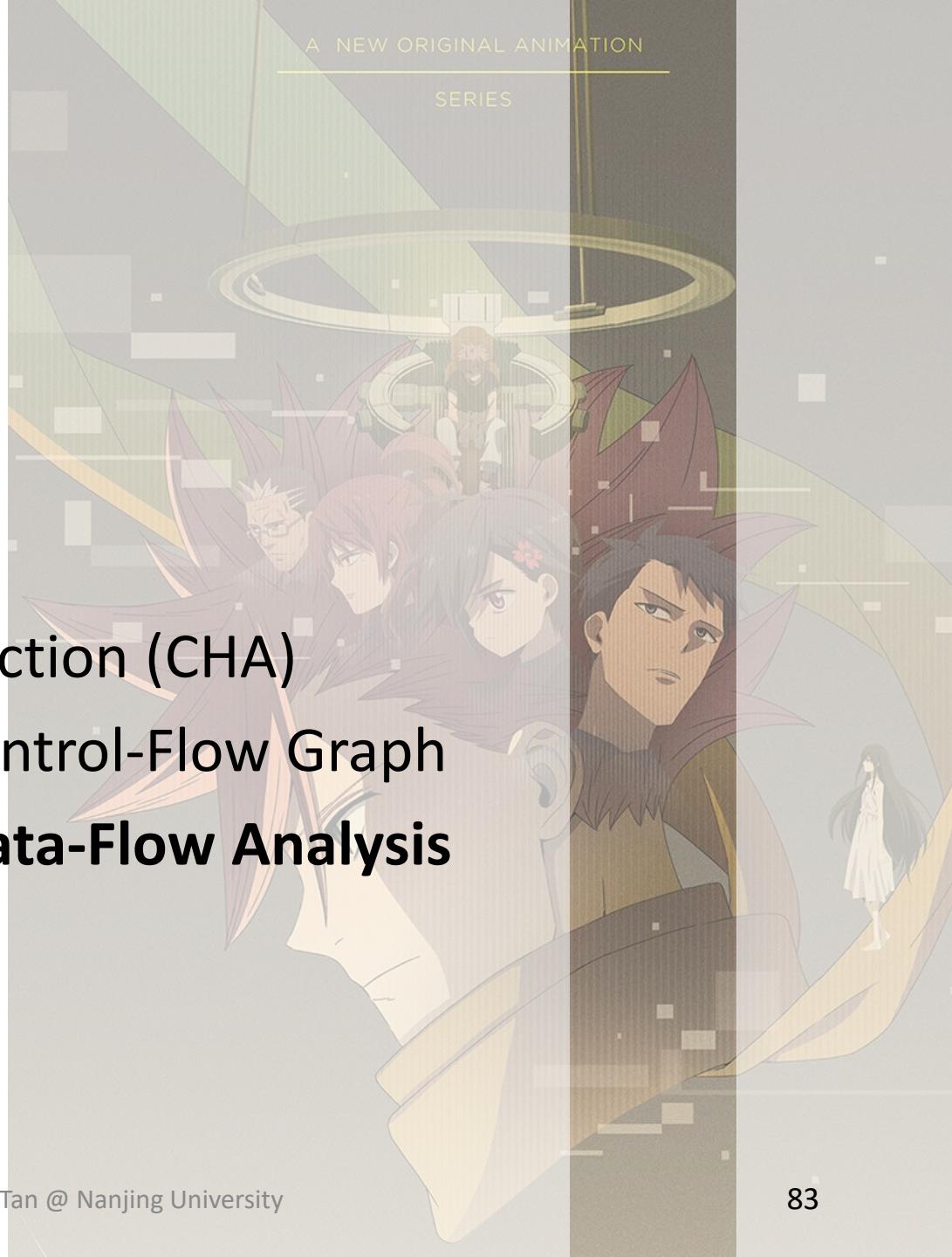


- CFG edges
- Normal edges →
- Call edges →
- Return edges →
- Call-to-return edges →

ICFG = CFGs + call & return edges

Contents

1. Motivation
2. Call Graph Construction (CHA)
3. Interprocedural Control-Flow Graph
4. **Interprocedural Data-Flow Analysis**



Interprocedural Data-Flow Analysis

Analyzing the whole program with method calls
based on interprocedural control-flow graph (ICFG)

	<i>Intraprocedural</i>	<i>Interprocedural</i>
Program representation	CFG	$\text{ICFG} = \text{CFGs} + \text{call \& return edges}$

Interprocedural Data-Flow Analysis

Analyzing the whole program with method calls
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	<i>Intraprocedural</i>	<i>Interprocedural</i>
Program representation	CFG	$\text{ICFG} = \text{CFGs} + \text{call \& return edges}$
Transfer functions	Node transfer	Node transfer + edge transfer

Interprocedural Data-Flow Analysis

Analyzing the whole program with method calls
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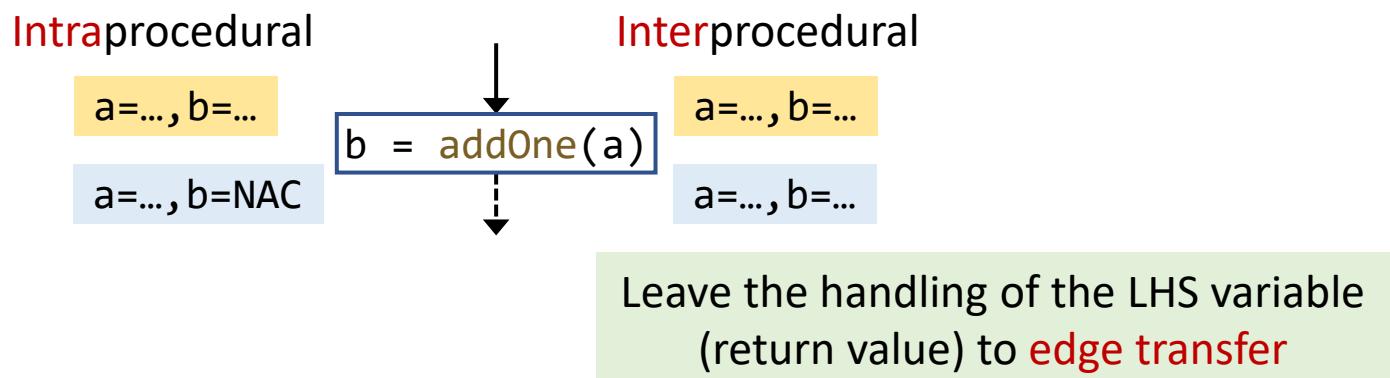
	<i>Intraprocedural</i>	<i>Interprocedural</i>
Program representation	CFG	$\text{ICFG} = \text{CFGs} + \text{call \& return edges}$
Transfer functions	Node transfer	Node transfer + edge transfer

Edge transfer

- **Call edge transfer**: transfer data flow from call site to the entry node of callee (along call edges)
- **Return edge transfer**: transfer data flow from exit node of the callee to the return site (along return edges)

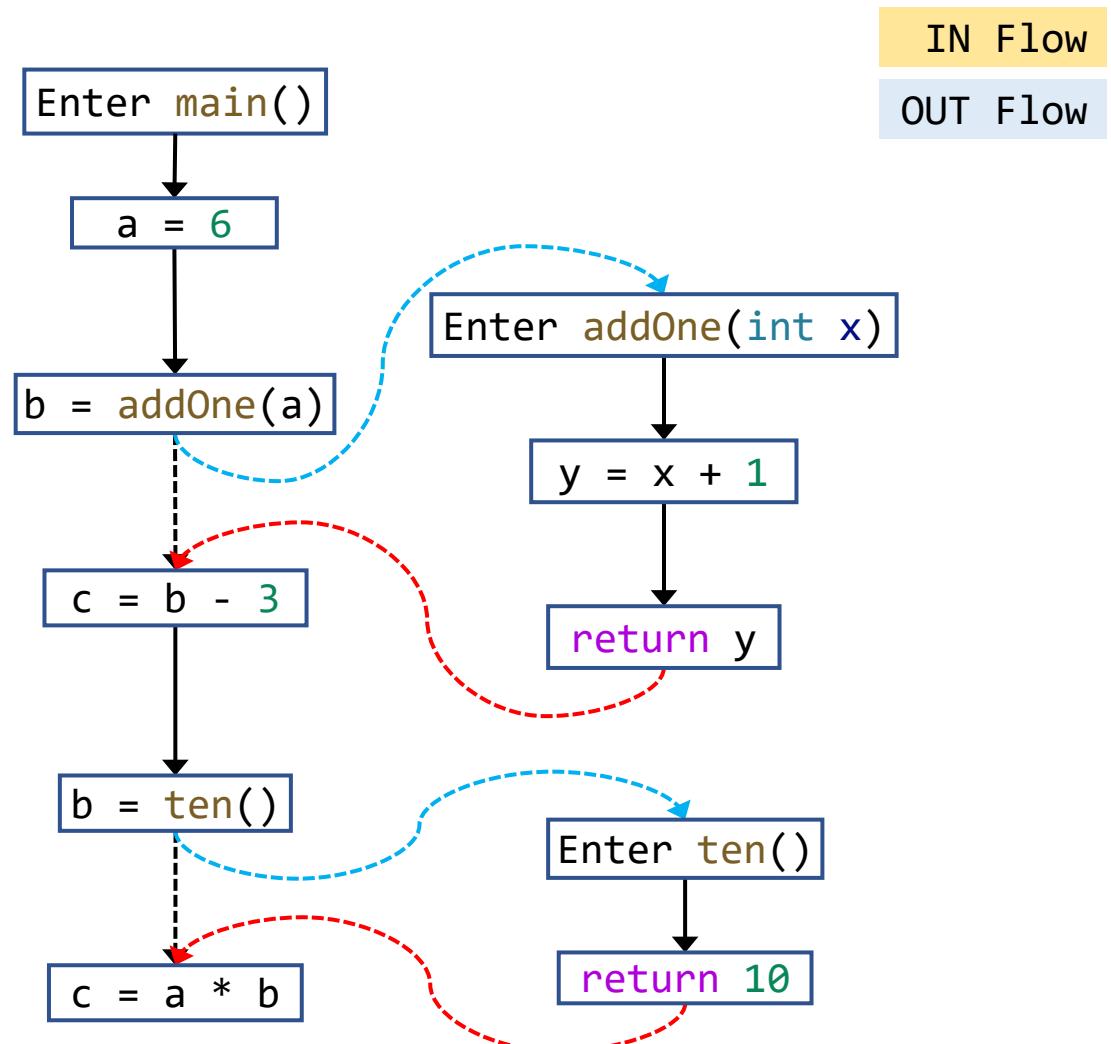
Interprocedural Constant Propagation

- Call edge transfer: pass argument values
- Return edge transfer: pass return values
- Node transfer: same as intraprocedural constant propagation, except that
 - For call nodes, the transfer function is *identity* function



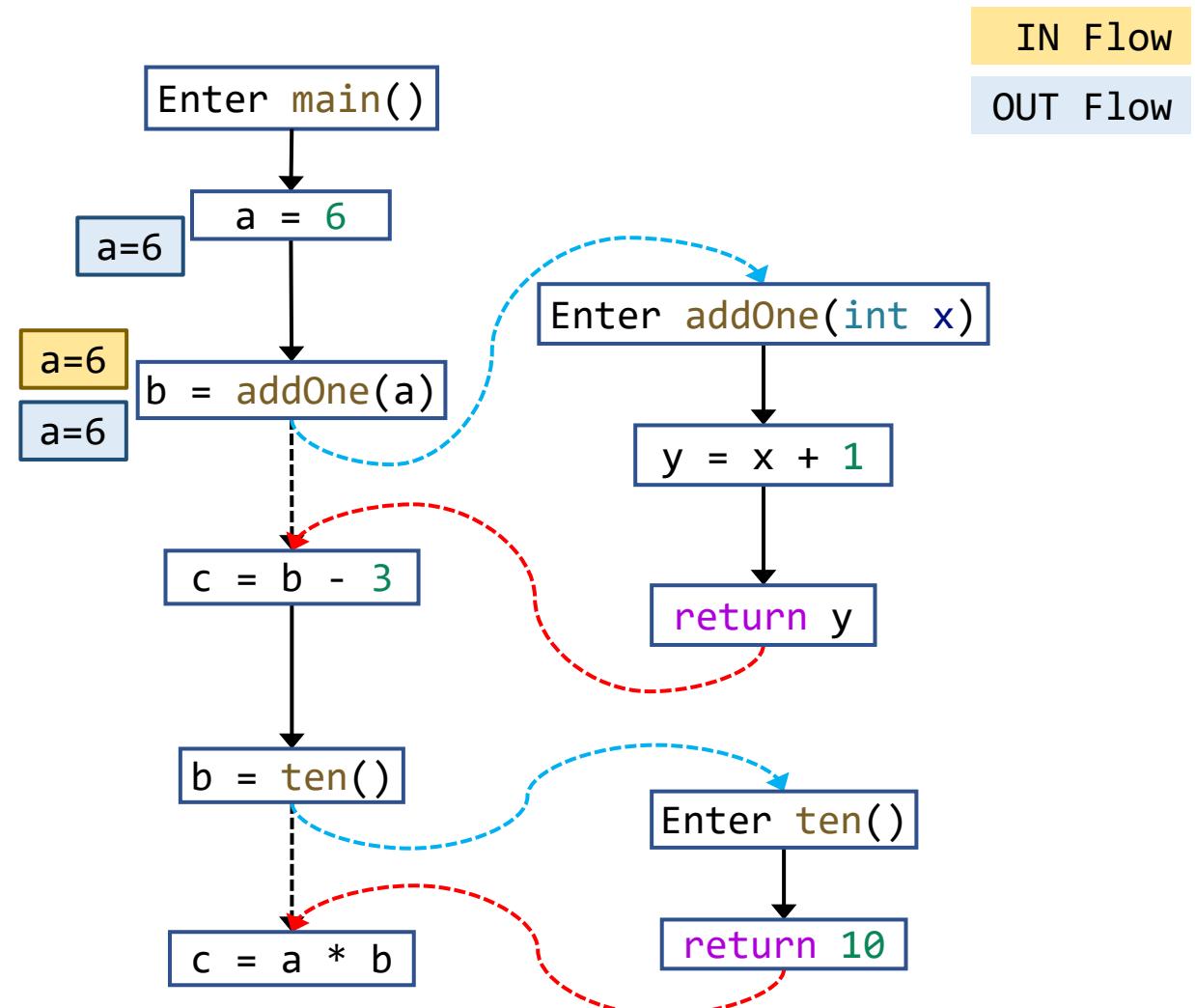
Interprocedural Constant Propagation: An Example

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static void main() {  
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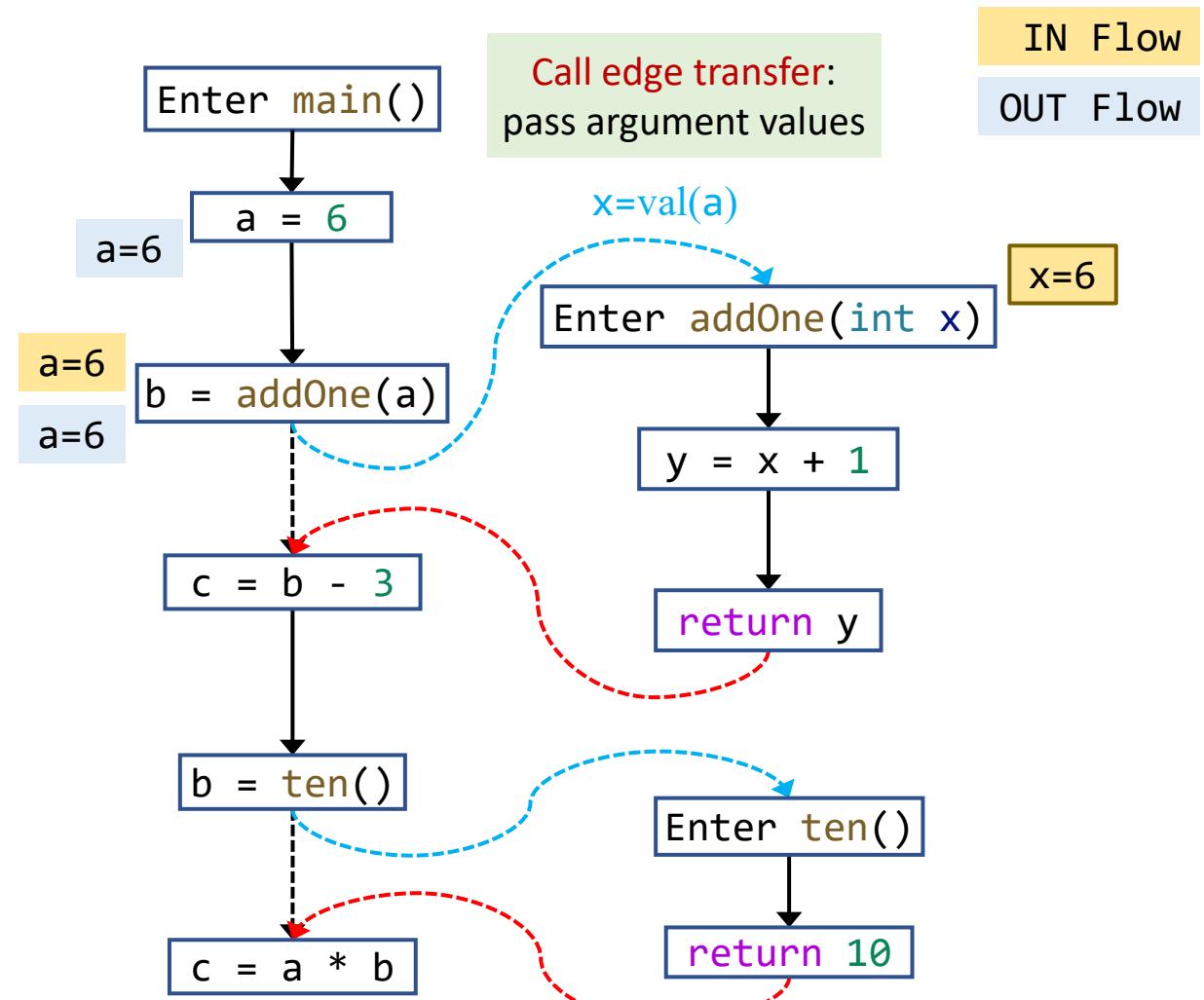
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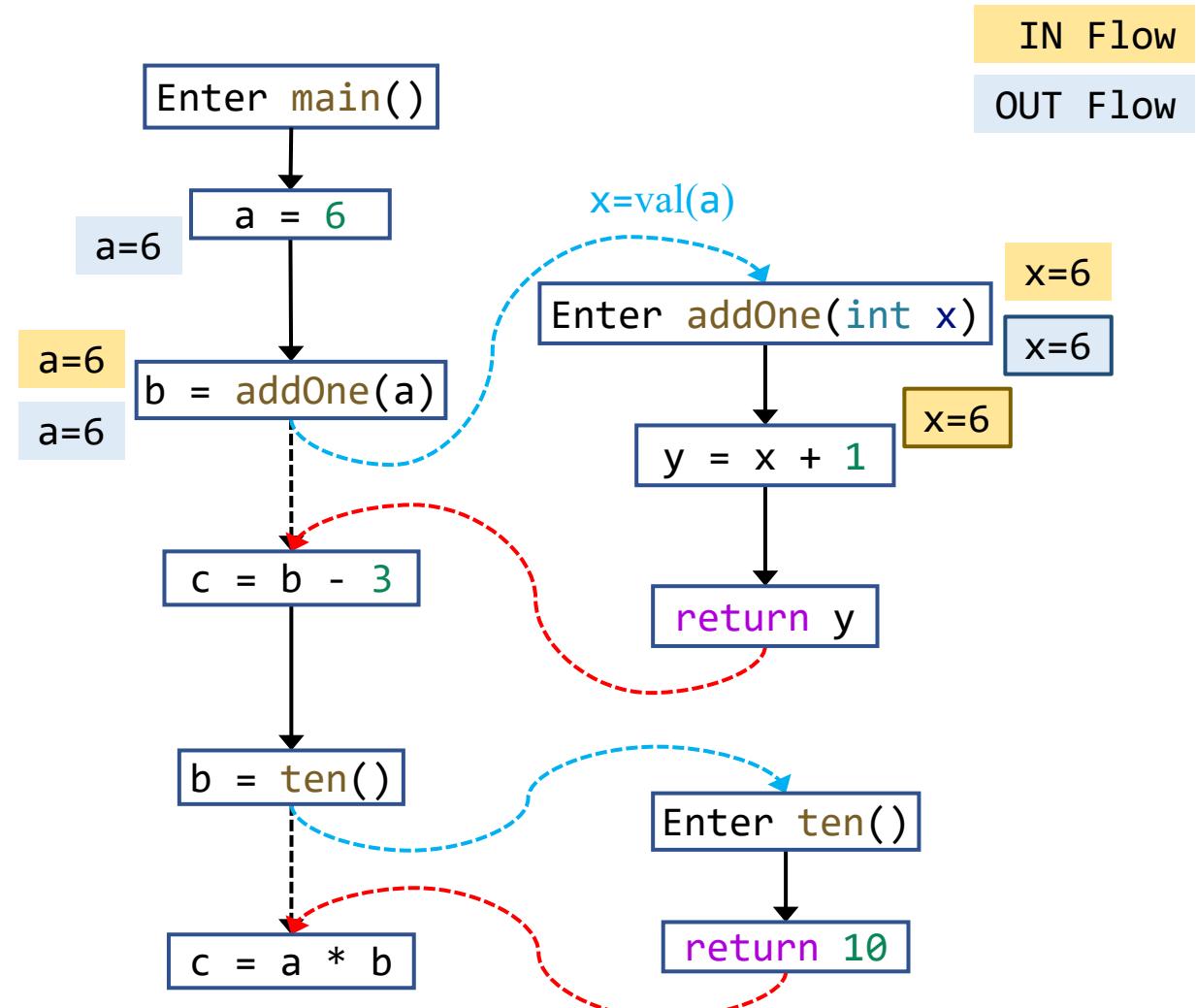
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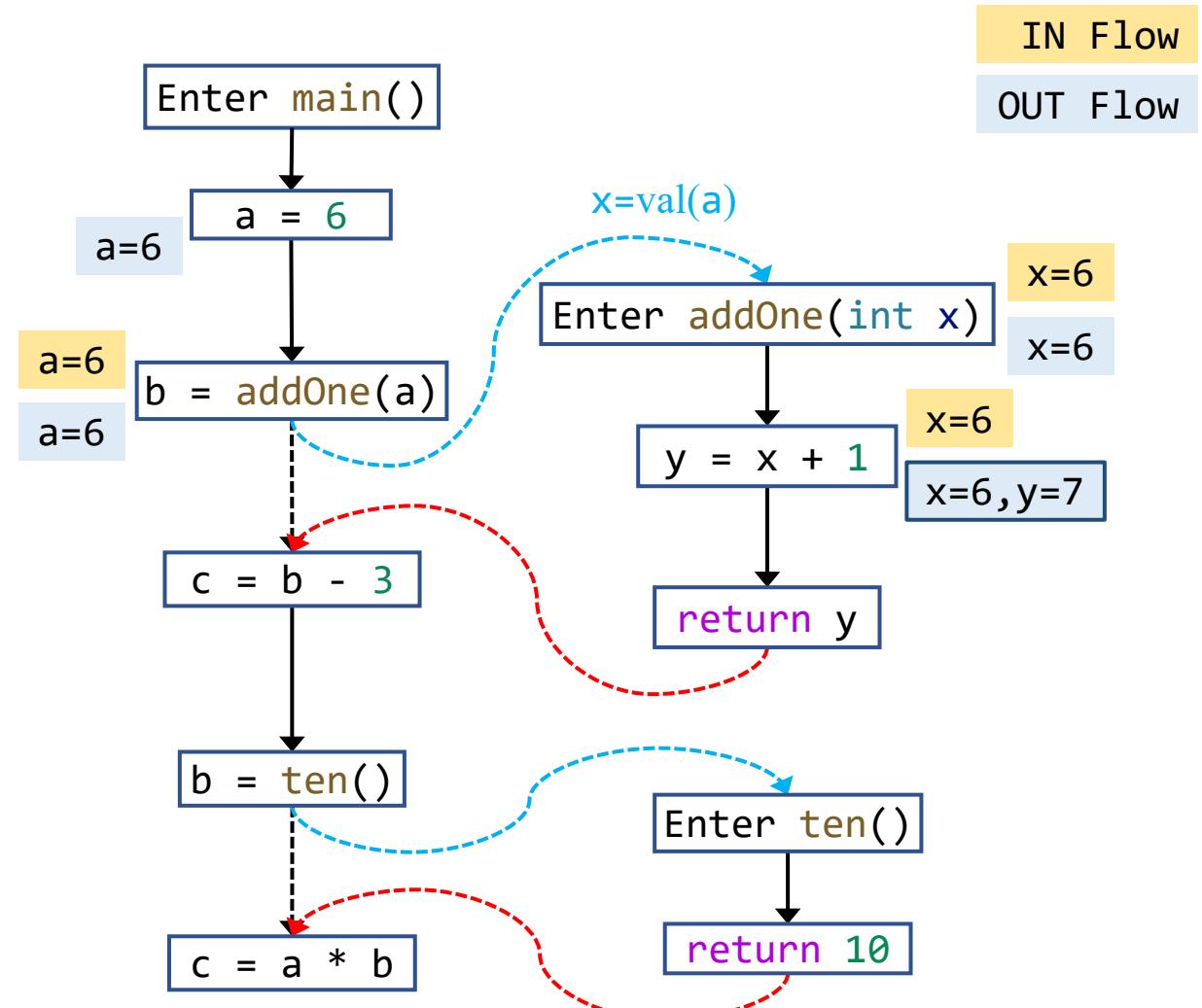
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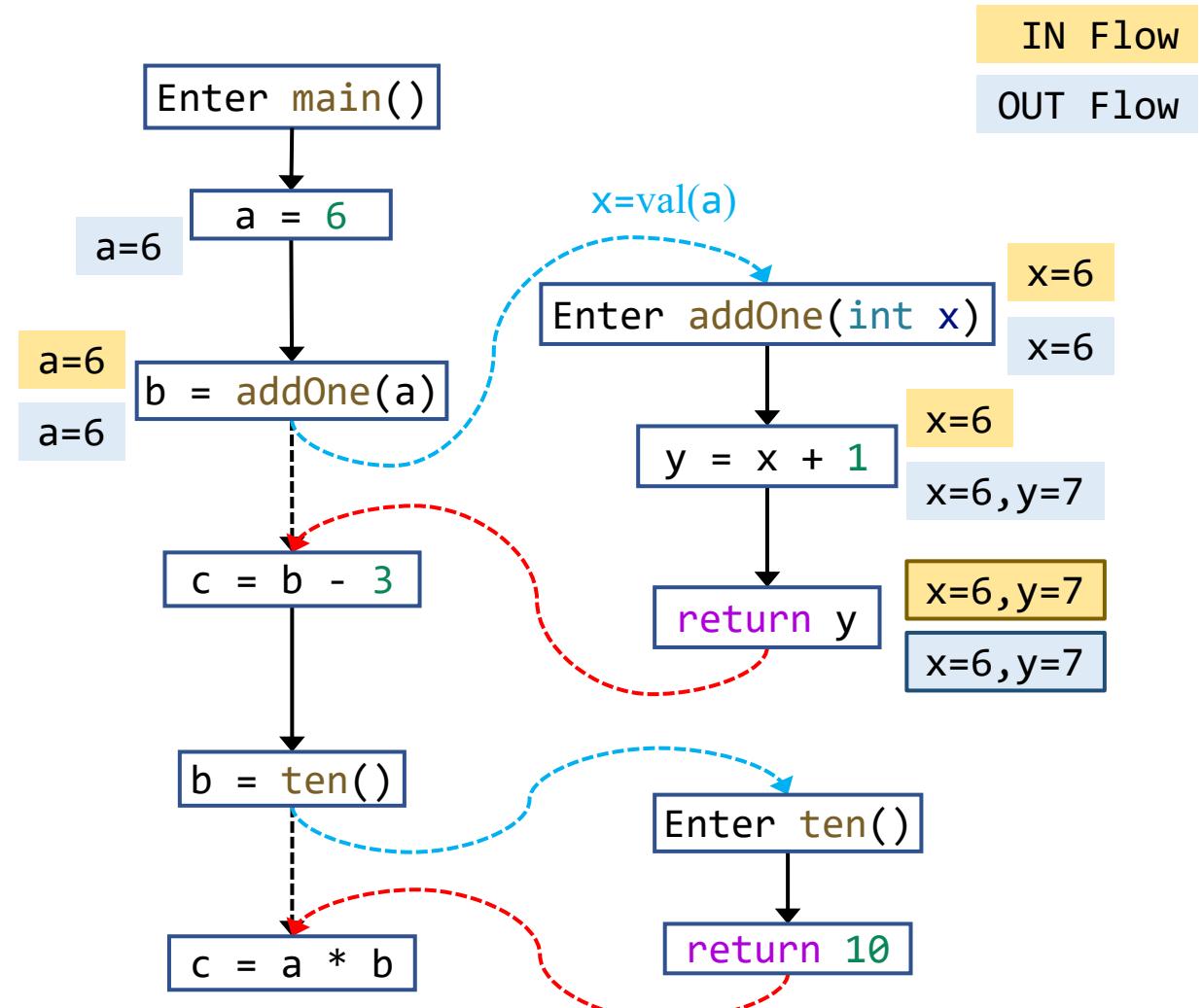
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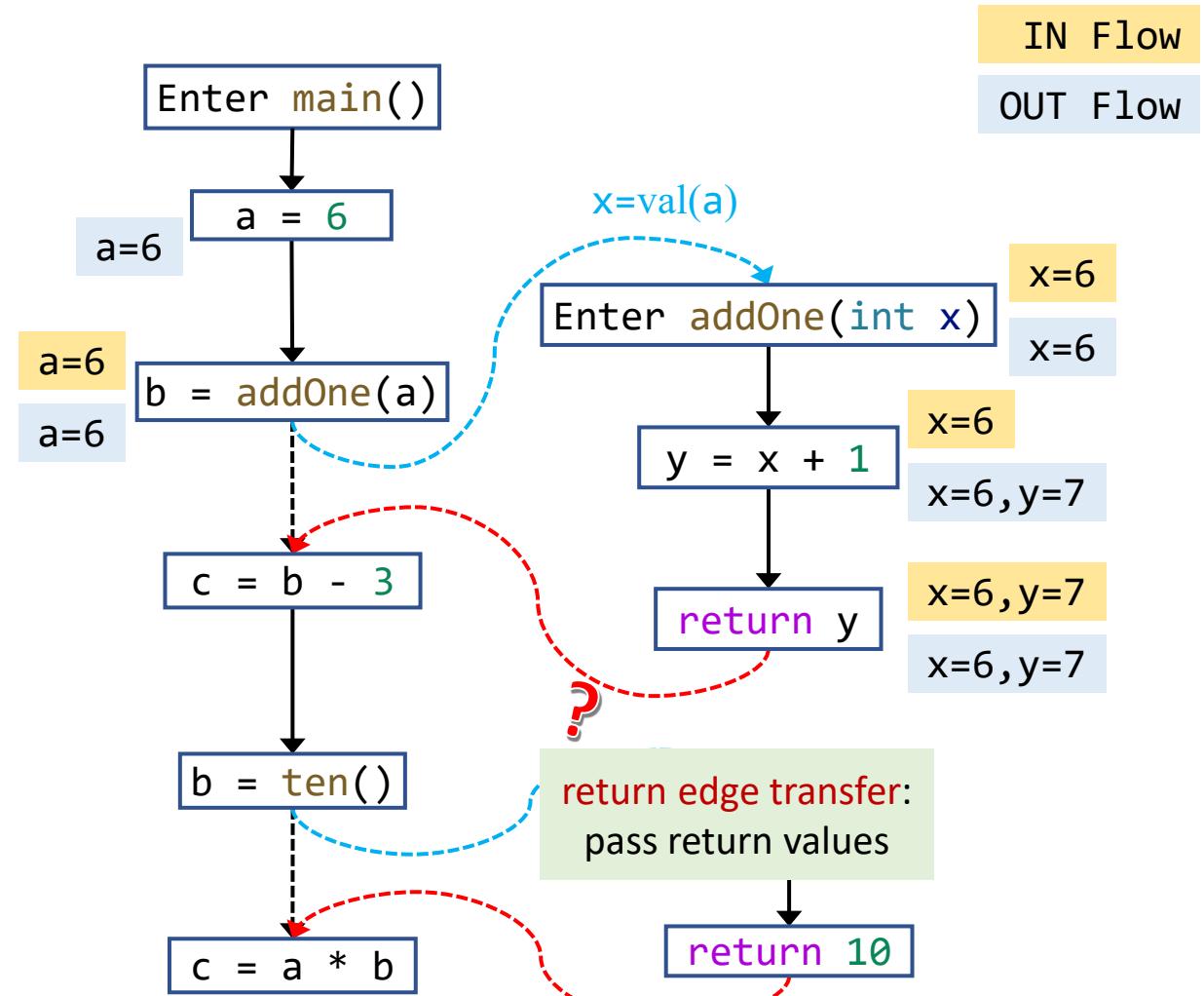
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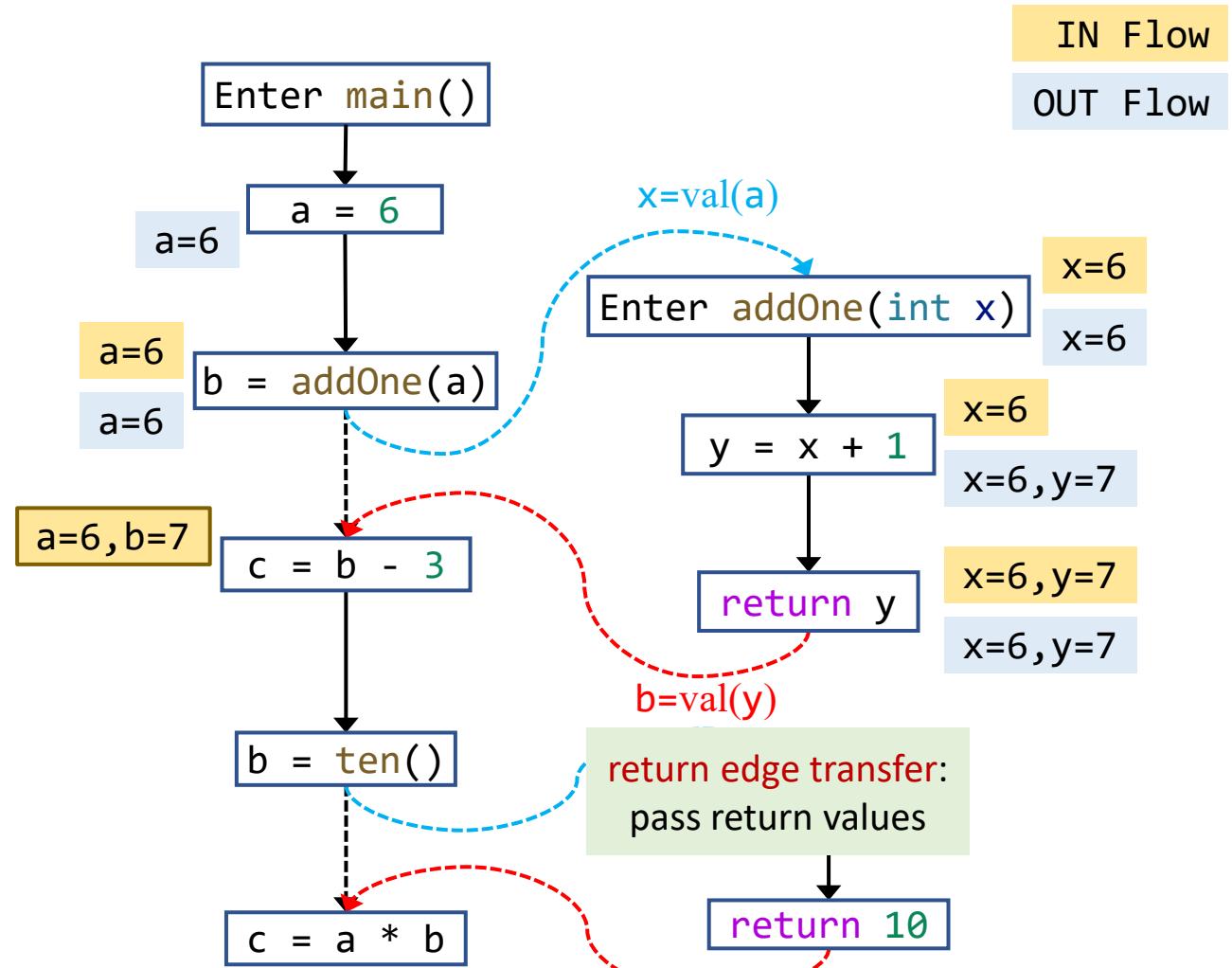
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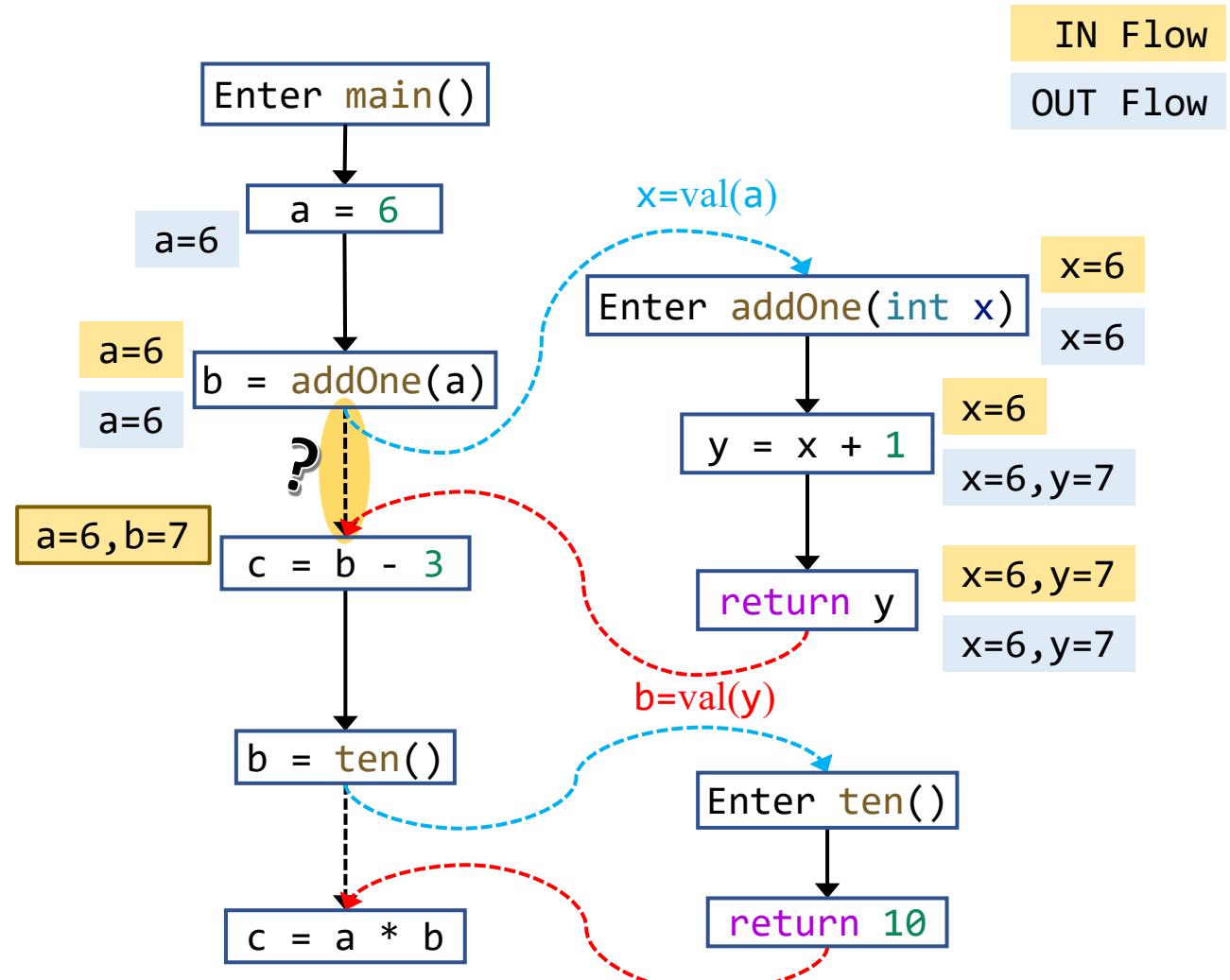
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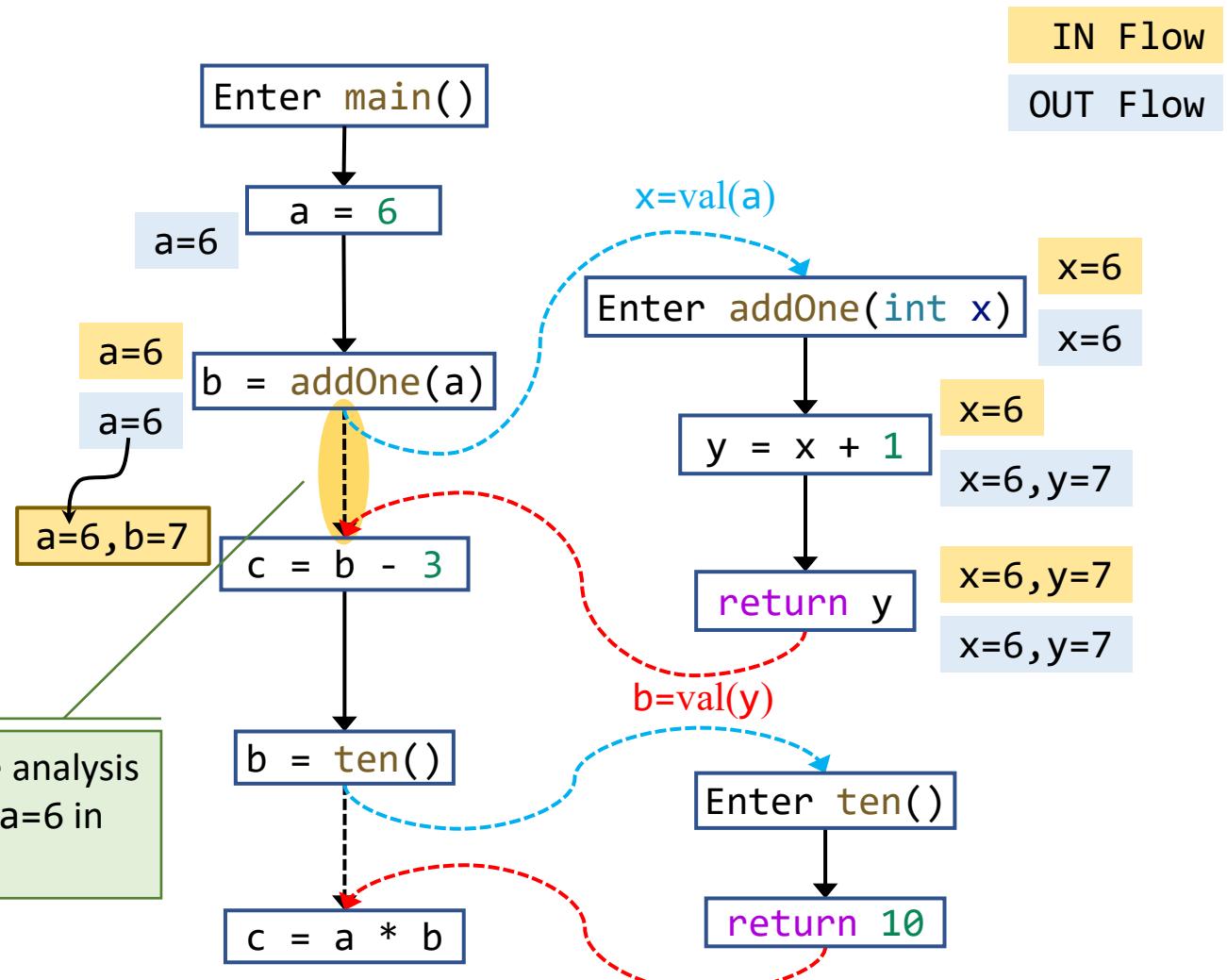


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Call-to-return edges allow the analysis to propagate local data-flow (a=6 in this case) on ICFG.



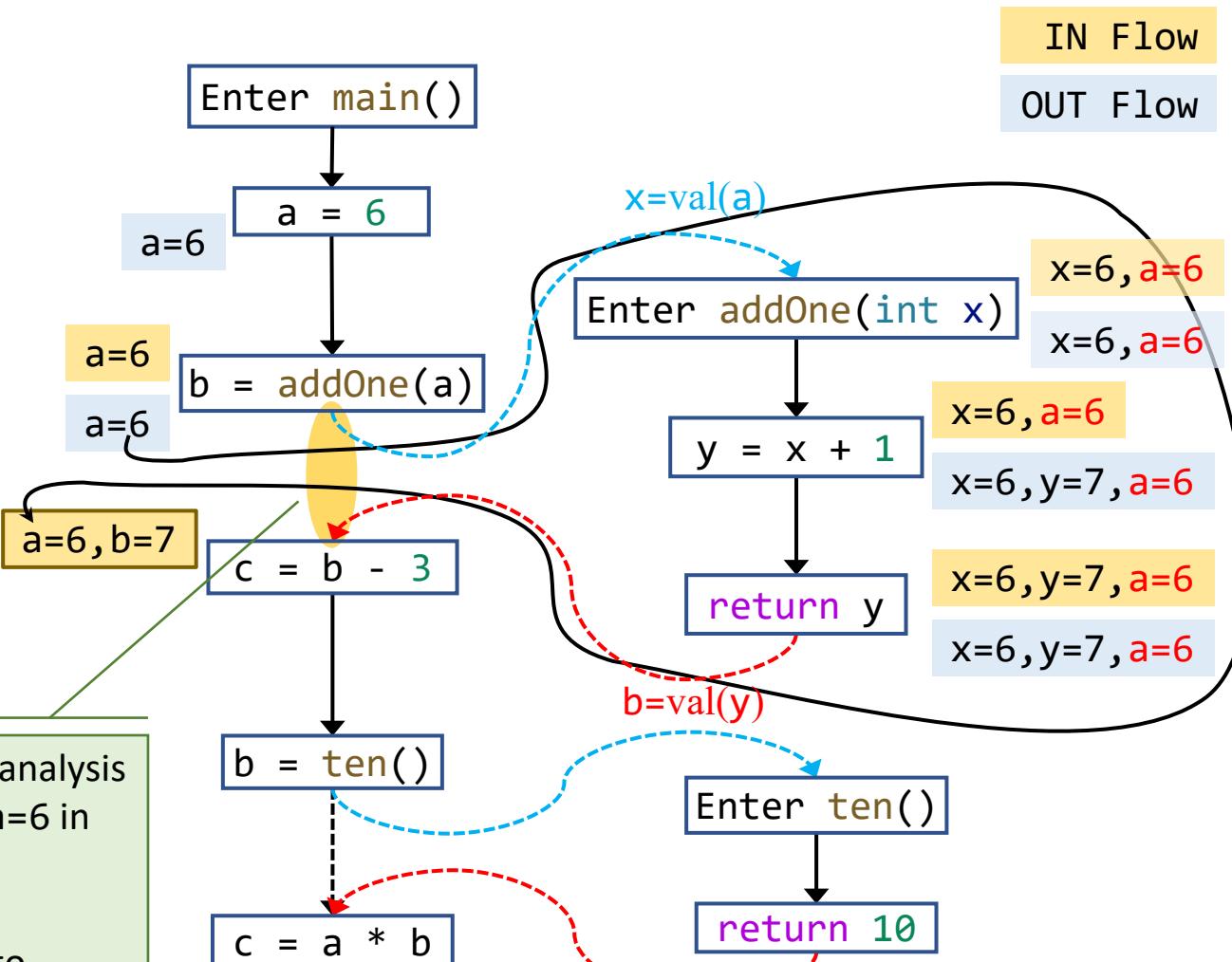
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Without such edges, we have to propagate local data-flow **across other methods**, which is **very inefficient**.



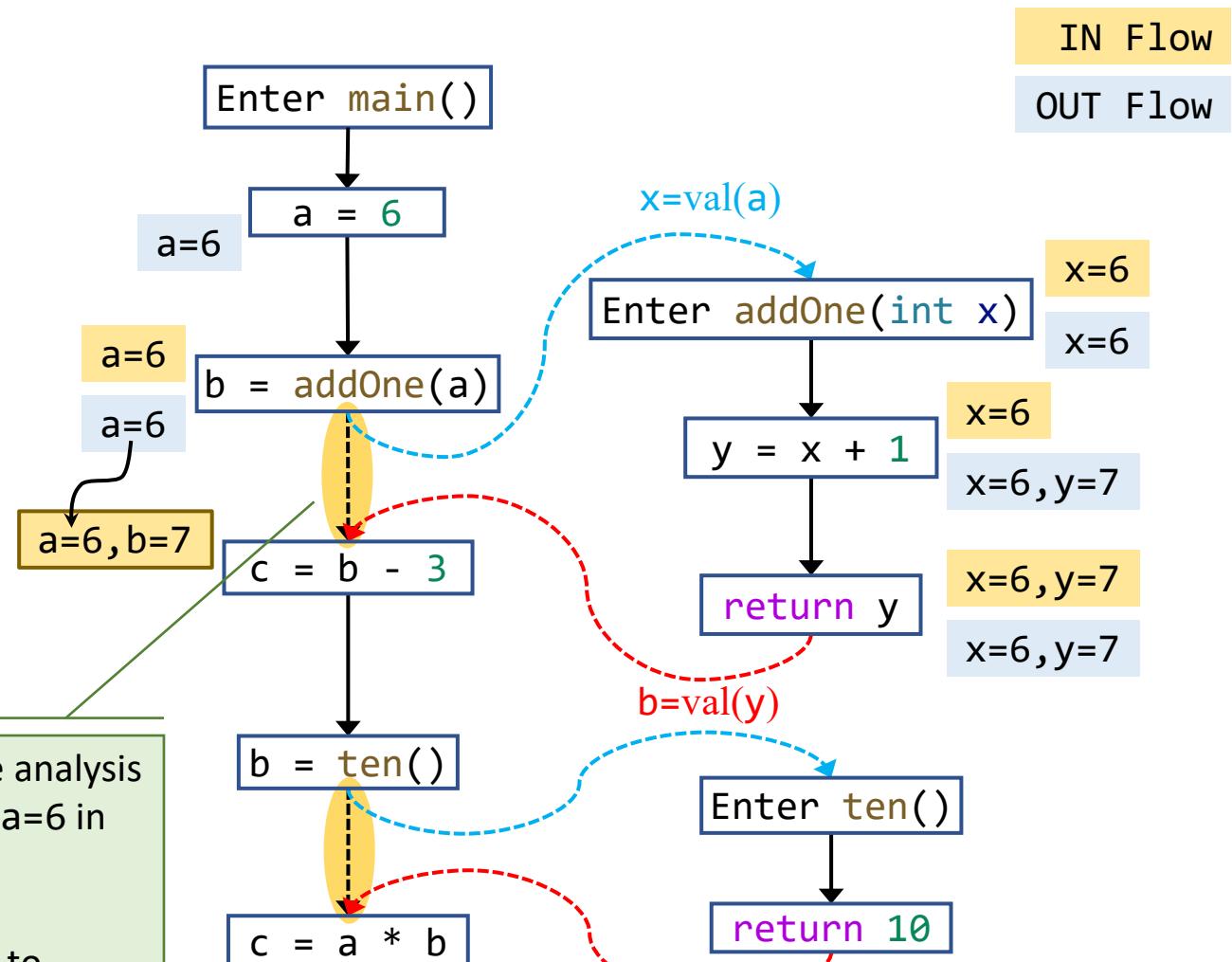
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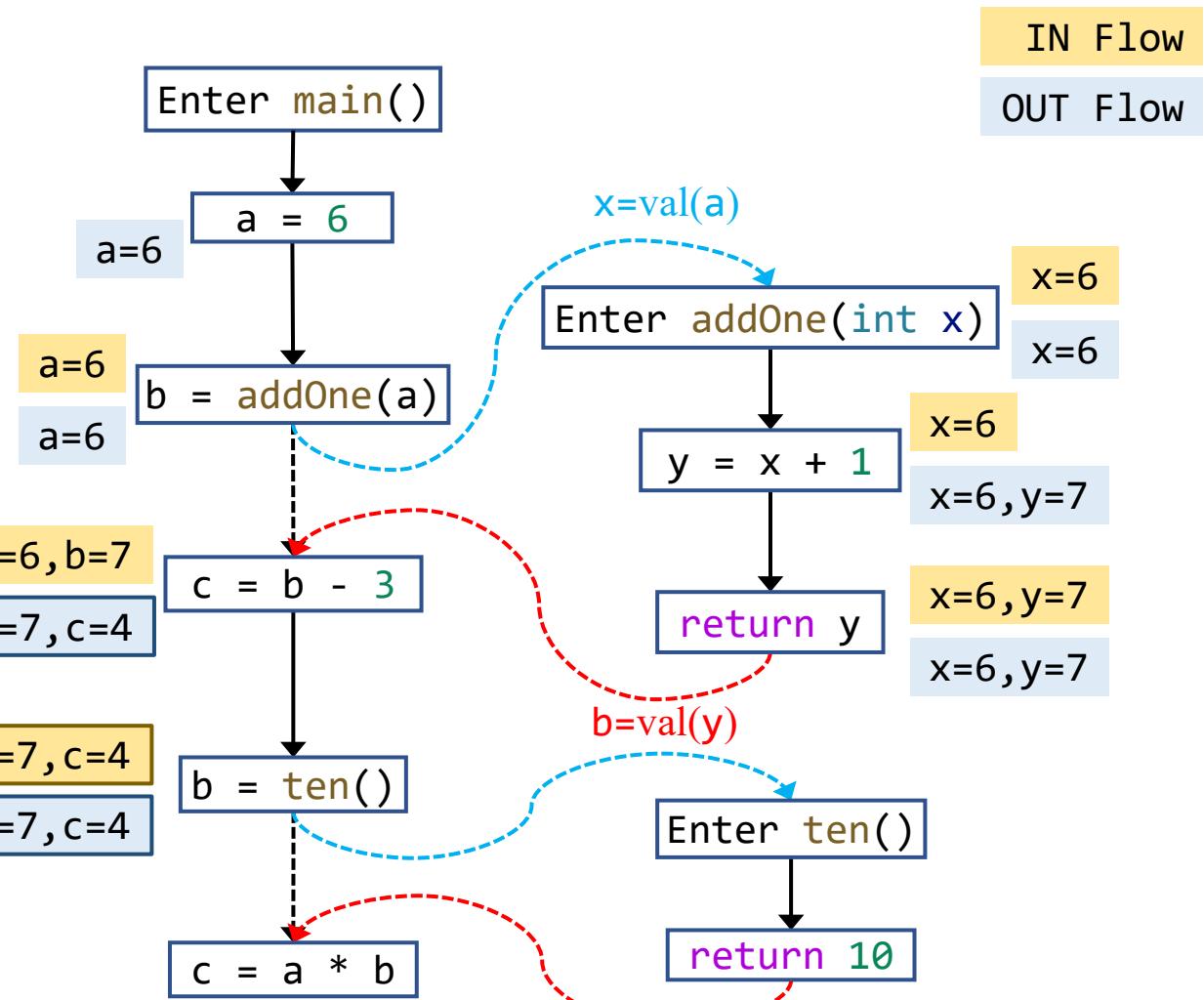


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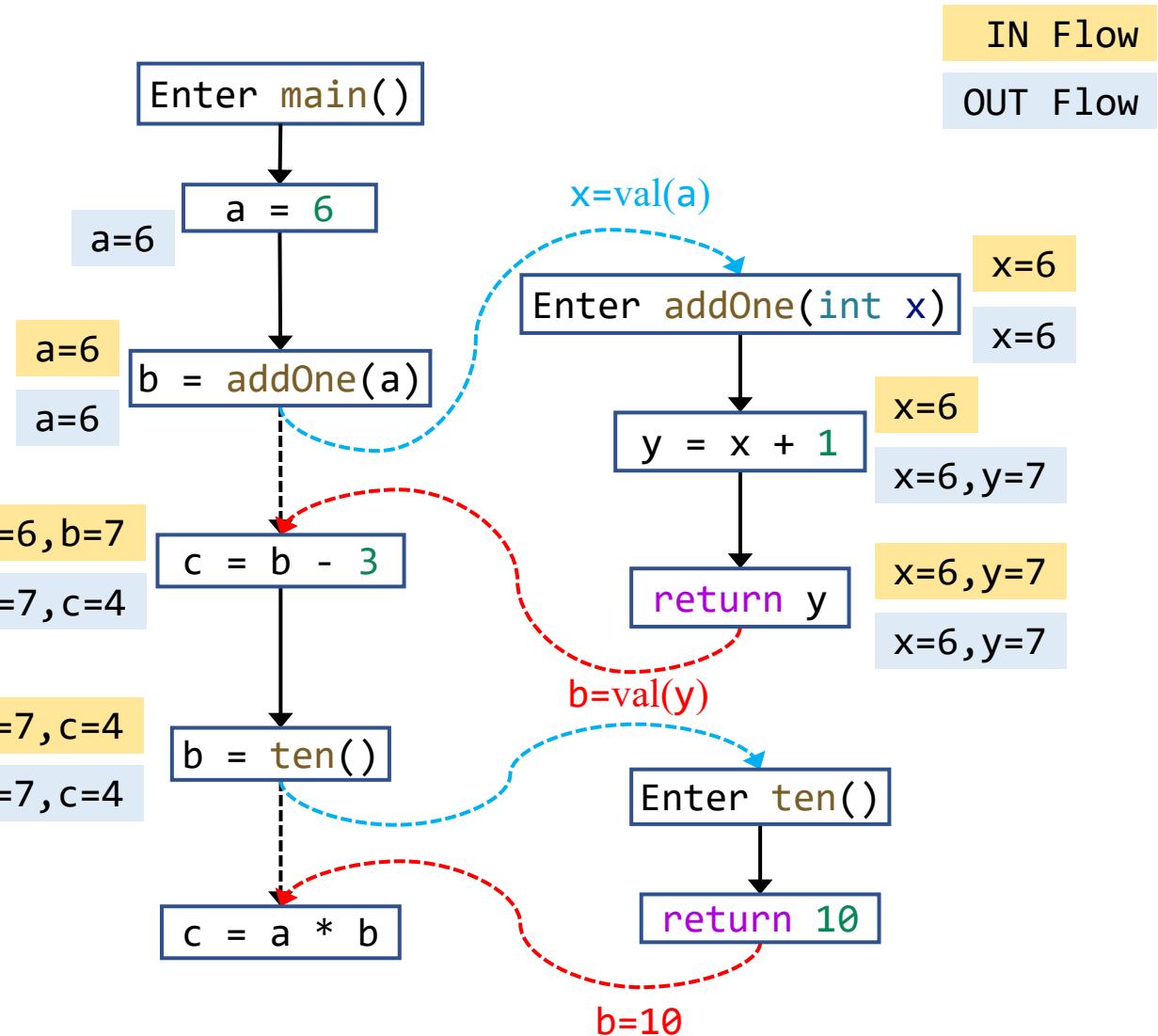


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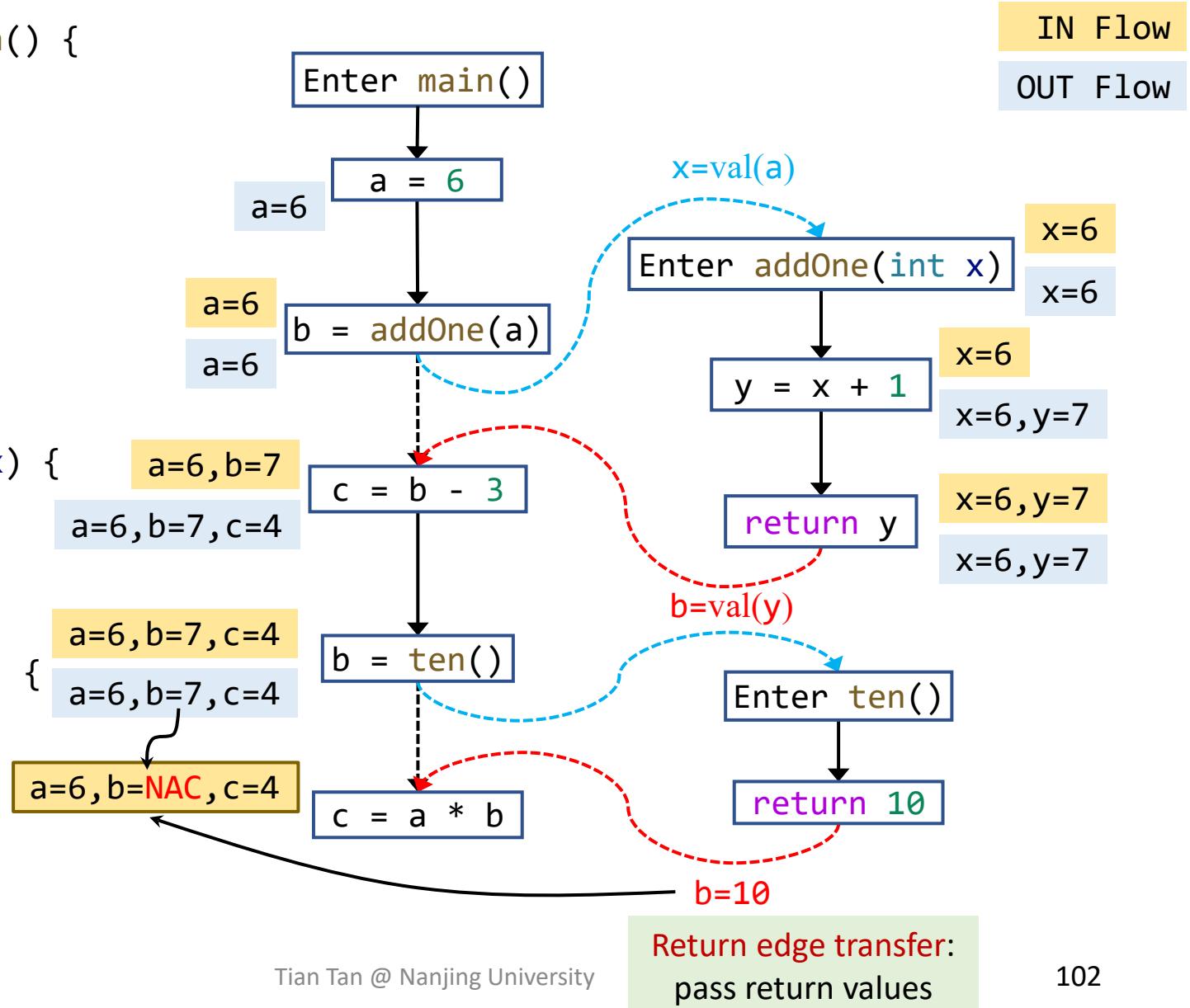


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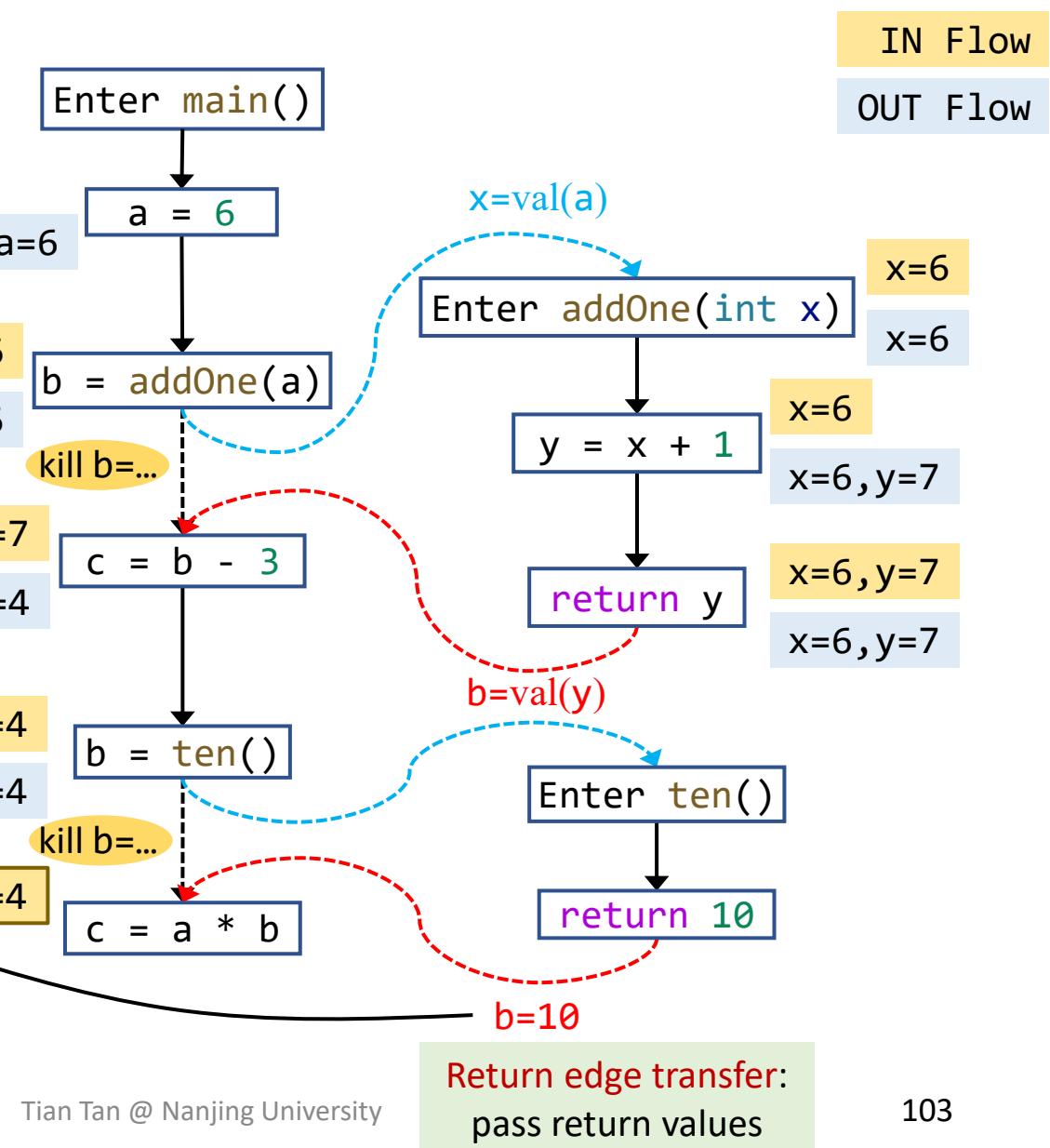
Interprocedural Constant Propagation: An Example

For call-to-return edge,
kill the value of the LHS variable of
the call site. Its value will flow to
return site along the return edges.
Otherwise, it may cause imprecision.

```
b = ten();  
c = a * b;  
}  
  
static  
int addOne(int x) {  
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Precise!

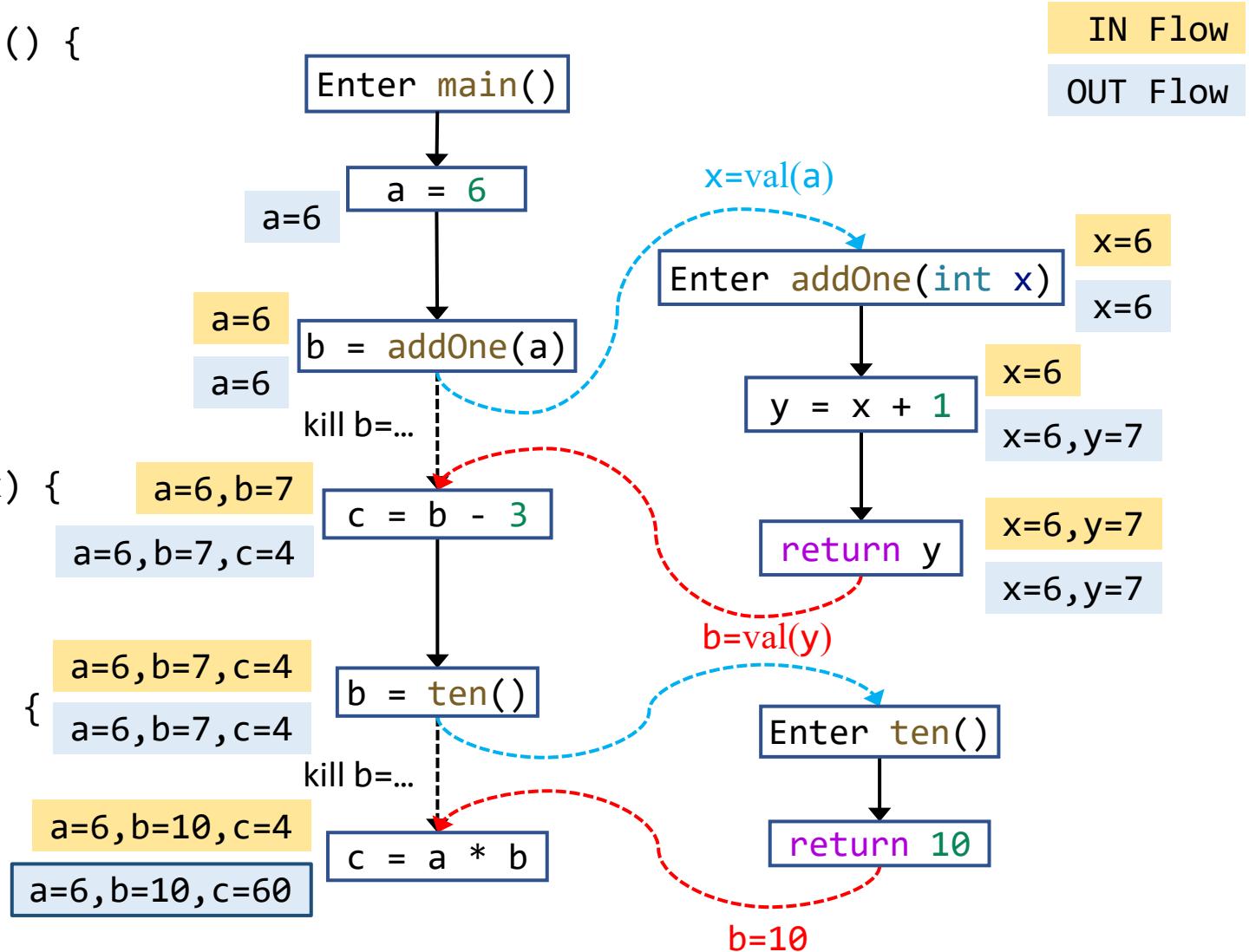


Interprocedural Constant Propagation: An Example

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```



Interprocedural Constant Propagation, In Summary

- Node transfer
 - Call nodes: identity
 - Other nodes: same as intraprocedural constant propagation
- Edge transfer
 - Normal edges: identity
 - Call-to-return edges: kill the value of LHS variable of the call site, propagate values of other local variables
 - Call edges: pass argument values
 - Return edges: pass return values

Intraprocedural Constant Propagation: An Example

```

static void main() {
    int a, b, c;
    a = 6;
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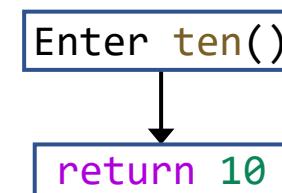
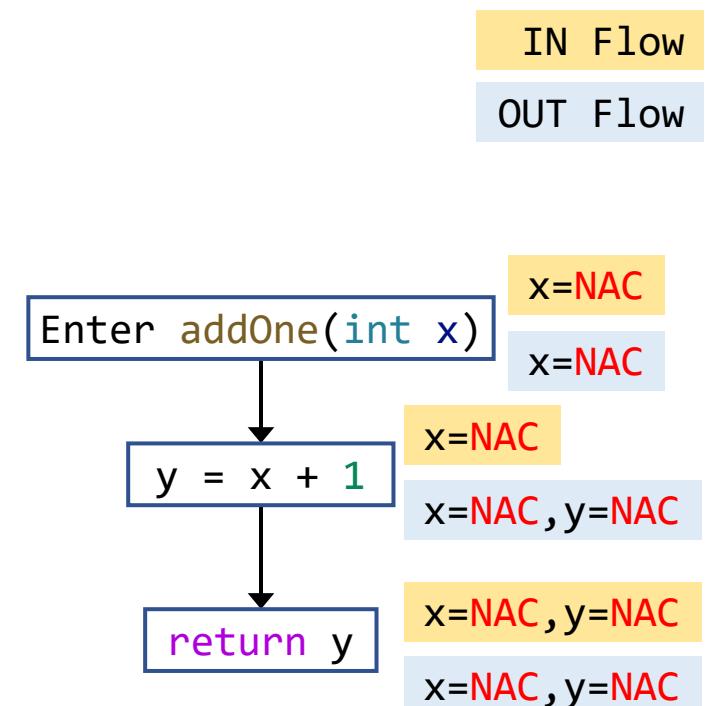
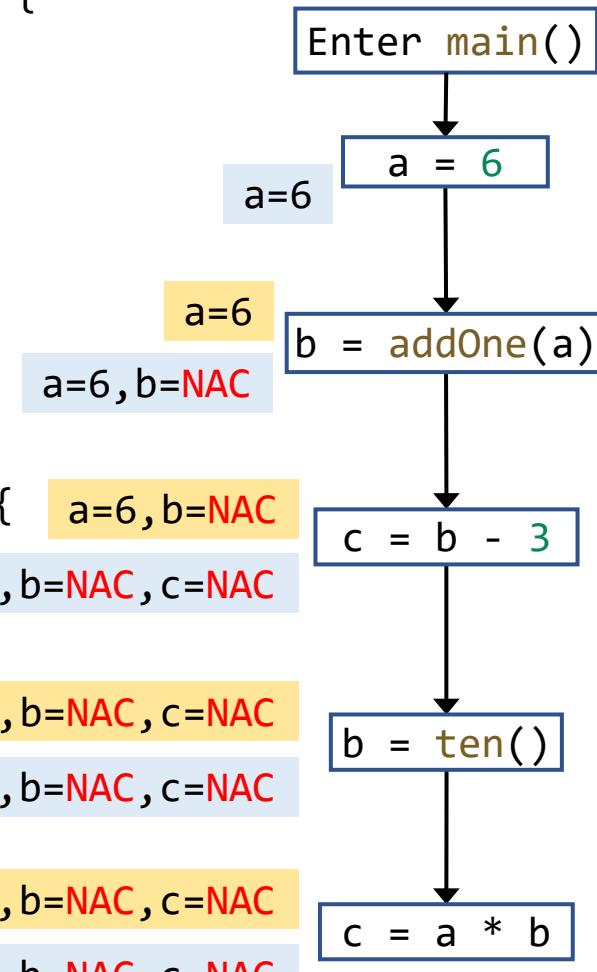
static int ten() {
    return 10;
}

```

```

a=6, b=NAC, c=NAC
a=6, b=NAC, c=NAC
a=6, b=NAC, c=NAC
a=6, b=NAC, c=NAC

```

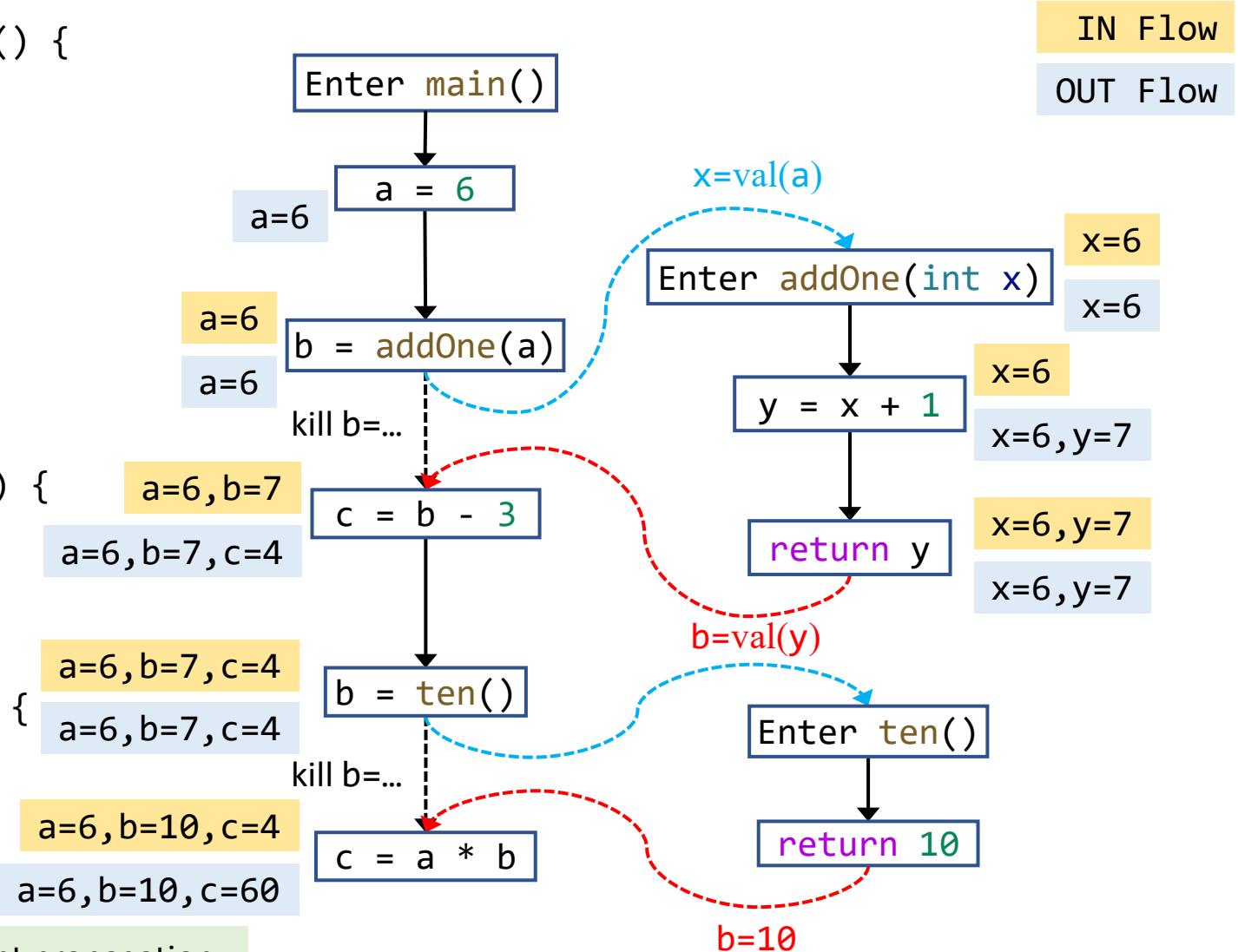


Interprocedural Constant Propagation: An Example

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Interprocedural constant propagation
is more precise than
Intraprocedural constant propagation

The X You Need To Understand in This Lecture

- How to build call graph via class hierarchy analysis
- Concept of interprocedural control-flow graph
- Concept of interprocedural data-flow analysis
- Interprocedural constant propagation

注意注意！
划重点了！

